

Monostable Multivibrator

The MC10198 is a retriggerable monostable multivibrator. Two enable inputs permit triggering on any combination of positive or negative edges. The trigger input is buffered by Schmitt triggers making it insensitive to input rise and fall times.

The pulse width is controlled by an external capacitor and resistor. The resistor sets a current which is the linear discharge rate of the capacitor. Also, the pulse width can be controlled by an external current source or voltage.

Rochester Electronics Manufactured Components

Rochester branded components are manufactured using either die/wafers purchased from the original suppliers or Rochester wafers recreated from the original IP. All recreations are done with the approval of the OCM.

Parts are tested using original factory test programs or Rochester developed test solutions to guarantee product meets or exceeds the OCM data sheet.

Quality Overview

- ISO-9001
- AS9120 certification
- Qualified Manufacturers List (QML) MIL-PRF-38535
 - Class Q Military
 - Class V Space Level
- Qualified Suppliers List of Distributors (QSLD)
 - Rochester is a critical supplier to DLA and meets all industry and DLA standards.

Rochester Electronics, LLC is committed to supplying products that satisfy customer expectations for quality and are equal to those originally supplied by industry manufacturers.

The original manufacturer's datasheet accompanying this document reflects the performance and specifications of the Rochester manufactured version of this device. Rochester Electronics guarantees the performance of its semiconductor products to the original OEM specifications. 'Typical' values are for reference purposes only. Certain minimum or maximum ratings may be based on product characterization, design, simulation, or sample testing.

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The MC10198 is a retriggerable monostable multivibrator. Two enable inputs permit triggering on any combination of positive or negative edges as shown in the accompanying table. The trigger input is buffered by Schmitt triggers making it insensitive to input rise and fall times.

The pulse width is controlled by an external capacitor and resistor. The resistor sets a current which is the linear discharge rate of the capacitor. Also, the pulse width can be controlled by an external current source or voltage (see applications information).

For high-speed response with minimum delay, a hi-speed input is also provided. This input bypasses the internal Schmitt triggers and the output responds within 2 nanoseconds typically.

Output logic and threshold levels are standard MECL 10,000. Test conditions are per Table 2. Each "Precondition" referred to in Table 2 is per the sequence of Table 1.

- $P_D = 415 \text{ mW typ/pkg (No Load)}$
- $t_{pd} = 4.0$ ns typ Trigger Input to Q
- 2.0 ns typ Hi-Speed Input to Q

• Min Timing Pulse Width	PW_{Qmin}	10 ns typ ¹
• Max Timing Pulse Width	PW_{Qmax}	$>10 \text{ ms typ}^2$
• Min Trigger Pulse Width	PW_T	2.0 ns typ
• Min Hi–Speed	PW_{HS}	3.0 ns typ
Trigger Pulse Width		
• Enable Setup Time	t _{set}	1.0 ns typ

thold

• Enable Hold Time



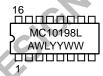
ON Semiconductor

http://onsemi.com

MARKING DIAGRAMS



CDIP-16 **L SUFFIX CASE 620**





PDIP-16 P SUFFIX **CASE 648**





PLCC-20 **FN SUFFIX CASE 775**



= Assembly Location

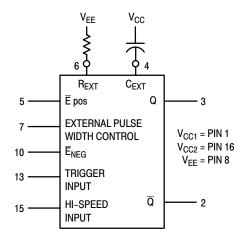
WL = Wafer Lot YY = Year WW = Work Week

ORDERING INFORMATION

Device	Package	Shipping
MC10198L	CDIP-16	25 Units / Rail
MC10198P	PDIP-16	25 Units / Rail
MC10198FN	PLCC-20	46 Units / Rail

1.0 ns typ

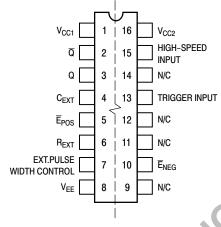
LOGIC DIAGRAM



TRUTH TABLE

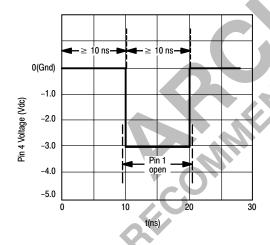
INPUT		OUTPUT
E _{Pos}	E _{Neg}	
L	L	Triggers on both positive & negative input slopes
L	Н	Triggers on positive input slope
Н	L	Triggers on negative input slope
Н	Н	Trigger is disabled

DIP **PIN ASSIGNMENT**



Pin assignment is for Dual-in-Line Package. For PLCC pin assignment, see the Pin Conversion Tables on page 18 of the ON Semiconductor MECL Data Book (DL122/D).

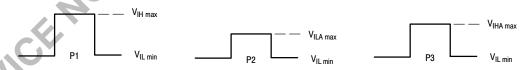
TABLE 1 — PRECONDITION SEQUENCE



- At t = 0a.) Apply V_{IHmax} to Pin 5 and 10.
 - b.) Apply V_{ILmin} to Pin 15.
 c.) Ground Pin 4.
- At $t \ge 10 \text{ ns}$ a.) Open Pin 1.
 - b.) Apply -3.0 Vdc to Pin 4. Hold these conditions for ≥10 ns.
- Return Pin 4 to Ground and perform test as indicated in Table 2.

TABLE 2 — CONDITIONS FOR TESTING OUTPUT LEVELS

(See Table 1 for Precondition Sequence)



Pins 1, $16 = V_{CC} = Ground$ Pins 6, $8 = V_{EE} = -5.2 \text{ Vdc}$ Outputs loaded 50 Ω to -2.0 Vdc

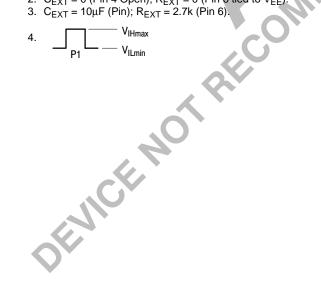
_	_		nditions	l		-	Pin
Test P.U	.T. 5	10	13	15	l	P.U.T. 5	+
Precondition			\ \/		Preconditi		
V _{OH} 2 V _{OH} 3			V _{IL min} P1		0.17	2 3	
recondition			''		Preconditi		
V _{OL} 3			V _{IL min}			3	
V _{OL} 2			P1		V _{OLA}	2	
Precondition				.,	Preconditi		
V _{OHA} 2 V _{OHA} 3				V _{ILA max} V _{IHA min}	OL/ (2 3	
Precondition				VIHA min	Preconditi		
V _{OHA} 2			$V_{IL\;min}$		02/1	3	
V _{OHA} 3			P3		, J_,	2	
Precondition V _{OHA} 2			P2		Preconditi	on 3	
V _{OHA} 2 V _{OHA} 3			P3		02.	2	
Precondition					Preconditi		
V _{OHA} 2		V _{IH max}	P2		02/1	3 V _{IHA min}	
V _{OHA} 3		V _{IH max}	P3		, J_,	2 V _{ILA max}	
Precondition V _{OHA} 2		V _{IH max}	P1		Preconditi V _{OLA}	3 V _{IH max}	
V _{OHA} 3		V _{IH max}	P1		V _{OLA}	2 V _{IH max}	
						€O,	
					OFF		
		•					
			CC				
		. 0					
		O					
	7						
V							
				-	-		

		Piı	Pin Conditions					
Test	P.U.T.	5	10	13	15			
Precond	dition							
V_{OHA}	2		$V_{IHA\ min}$	P1				
V_{OHA}	3		V _{ILA max}	P1				
Precond	dition							
V_{OLA}	3				V _{ILA max}			
V_{OLA}	2				$V_{IHA\ min}$			
Precond	dition							
V_{OLA}	2			$V_{IL\ min}$				
V_{OLA}	3			$V_{IL\ min}$				
Precond	dition							
V_{OLA}	3			P2				
V_{OLA}	2			P3				
Precond	dition							
V_{OLA}	3		V _{IH max}	P2				
V_{OLA}	2		V _{IH max}	P3				
Precond	dition			.63				
V_{OLA}	3	$V_{IHA\ min}$	V _{IH max}	P1				
V_{OLA}	2	V _{ILA max}	V _{IH max}	P1				
Precond	dition							
V_{OLA}	3	V _{IH max}	$V_{IHA\ min}$	P1				
V _{OLA}	2	V _{IH max}	V _{ILA max}	P1				

ELECTRICAL CHARACTERISTICS

					7	Test Limits	3			
		Pin Under	-30	0°C		+25°C		+85	5°C	
Characteristic	Symbol	Test	Min	Max	Min	Тур	Max	Min	Max	Unit
Power Supply Drain Current	Ι _Ε	8		110		80	100		110	mAdc
Input Current	l _{inH}	5, 10 13 15		415 350 560			260 220 350		260 220 350	μAdc
	I _{inL}	5	0.5		0.5			0.3		μAdc
Output Voltage Logic 1	V _{OH}	2 3	-1.060 -1.060	-0.890 -0.890	-0.960 -0.960		-0.810 -0.810	-0.890 -0.890	-0.700 -0.700	Vdc
Output Voltage Logic 0	V _{OL}	2 3	-1.890 -1.890	-1.675 -1.675	-1.850 -1.850		-1.650 -1.650	-1.825 -1.825	-1.615 -1.615	Vdc
Threshold Voltage Logic 1	V_{OHA}	2 3	-1.080 -1.080		-0.980 -0.980			-0.910 -0.910		Vdc
Threshold Voltage Logic 0	V _{OLA}	2 3		-1.655 -1.655			-1.630 -1.630		-1.595 -1.595	Vdc
Switching Times (50 Ω Load)										
Trigger Input	t _{T+Q+} t _{T-Q+}	3 3	2.5 2.5	6.5 6.5	2.5 2.5	4.0 4.0	5.5 5.5	2.5 2.5	6.5 6.5	ns
High Speed Trigger Input	t _{HS+Q+}	3	1.5	3.2	1.5	2.0	2.8	1.5	3.2	ns
Minimum Timing Pulse Width	PW_{Qmin}	3				10.0				ns
Maximum Timing Pulse Width	PW _{Qmax}	3				>10				ms
Min Trigger Pulse Width	PW_T	3			*	2.0				ns
Min Hi-Spd Trig Pulse Width	PW _{HS}	3				3.0				ns
Rise Time (20 to 80%)		3	1.5	4.0	1.5		3.5	1.5	4.0	ns
Fall Time (20 to 80%)		3	1.5	4.0	1.5		3.5	1.5	4.0	ns
Enable Setup Time	t _{setup} (E)	3		62.		1.0				ns
Enable Hold Time	t _{hold} (E)	3				1.0				ns

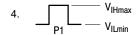
The monostable is in the timing mode at the time of this test.
 C_{EXT} = 0 (Pin 4 Open); R_{EXT} = 0 (Pin 6 tied to V_{EE}).
 C_{EXT} = 10μF (Pin); R_{EXT} = 2.7k (Pin 6).



ELECTRICAL CHARACTERISTICS (continued)

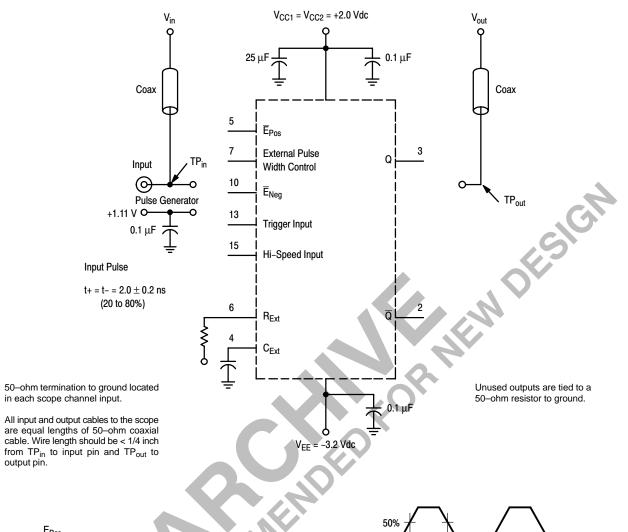
				TEST VOLTAGE VALUES (Volts)					
		@ Test Ten	nperature	V _{IHmax}	V _{ILmin}	V _{IHAmin}	V _{ILAmax}	V _{EE}	
			–30°C	-0.890	-1.890	-1.205	-1.500	-5.2	
			+25°C	-0.810	-1.850	-1.105	-1.475	-5.2	
			+85°C	-0.700	-1.825	-1.035	-1.440	-5.2	
			Pin	TEST VOLTAGE APPLIED TO PINS LISTED BELOW					<i>~</i>
Characteristic		Symbol	Under Test	V _{IHmax}	V _{ILmin}	V _{IHAmin}	V _{ILAmax}	V _{EE}	(V _{CC}) Gnd
Power Supply Drain Current		ΙE	8					6, 8	1, 4, 16
Input Current		I _{inH}	5, 10 13 15	5,10 13 15				6, 8 6, 8 6, 8	1, 4, 16 1, 4, 16 1, 4, 16
		I _{inL}	5		5			6, 8	1, 4, 16
Output Voltage L	ogic 1	V _{OH}	2 3	13 (4.)	13			6, 8 6, 8	1, 4, 16 1, 4, 16
Output Voltage L	ogic 0	V _{OL}	2 3	13 (4.)	13			6, 8 6, 8	1, 4, 16 1, 4, 16
Threshold Voltage L	₋ogic 1	V _{OHA}	2 3			15	15	6, 8 6, 8	1, 16, 4 1, 16, 4
Threshold Voltage L	ogic 0	V_{OLA}	2 3			15	15	6, 8 6, 8	1, 16, 4 1, 16, 4
Switching Times (50Ω	Load)			+1.11V		Pulse In	Pulse Out	-3.2 V	+2.0 V
Trigger Input		$t_{T+Q+} \ t_{T-Q+}$	3 3	10 5		13 13	3 3	6, 8 6, 8	1, 16, 4 1, 16, 4
High Speed Trigger Input		t _{HS+Q+}	3		> <	15	3	6, 8	1, 16, 4
Minimum Timing Pulse Width		PW_{Qmin}	3				Note 2.	6, 8	1, 16, 4
Maximum Timing Pulse Width		PW _{Qmax}	3				Note 3.	6, 8	1, 16, 4
Minimum Trigger Pulse Width		PW_T	3			13	3	6, 8	1, 16, 4
Minimum Hi-Spd Trigger Puls Width	е	PW _{HS}	3			15	3	6, 8	1, 16, 4
Rise Time (20 to	80%)		3					6, 8	1, 16, 4
Fall Time (20 to	80%)		3					6, 8	1, 16, 4
Enable Setup Time		t _{setup} (E)	3			5	3	6, 8	1, 16, 4
Enable Hold Time		t _{hold} (E)	3			5	3	6, 8	1, 16, 4

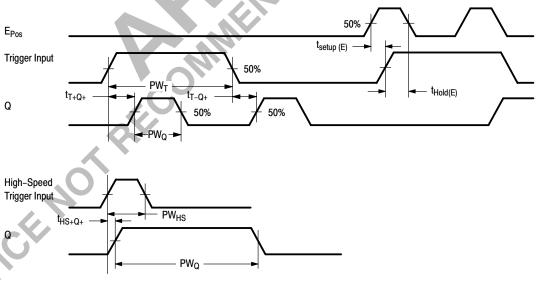
- 1. The monostable is in the timing mode at the time of this test.
- 2. $C_{EXT} = 0$ (Pin 4 Open); $R_{EXT} = 0$ (Pin 6 tied to V_{EE}). 3. $C_{EXT} = 10\mu F$ (Pin); $R_{EXT} = 2.7k$ (Pin 6).



Each MECL 10,000 series circuit has been designed to meet the dc specifications shown in the test table, after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse air flow greater than 500 linear fpm is maintained. Outputs are terminated through a 50-ohm resistor to -2.0 volts. Test procedures are shown for only one gate. The other gates are tested in the same manner.

SWITCHING TIME TEST CIRCUIT AND WAVEFORMS @ 25°C





APPLICATIONS INFORMATION

Circuit Operation:

1. PULSE WIDTH TIMING — The pulse width is determined by the external resistor and capacitor. The MC10198 also has an internal resistor (nominally 284 ohms) that can be used in series with R_{Ext}. Pin 7, the external pulse width control, is a constant voltage node (-3.60 V nominally). A resistance connected in series from this node to V_{EE} sets a constant timing current I_T. This current determines the discharge rate of the capacitor:

where

$$\Delta T = \text{pulse width}$$

 $\Delta V = 1.9 \text{ V}$ change in capacitor voltage

Then:
$$I_T = C_{Ext}$$
 $\frac{\Delta V}{\Delta T}$

If $R_{Ext} + R_{Int}$ are in series to V_{EE} :

$$\begin{split} I_T &= [(-3.60 \text{ V}) - (-5.2 \text{ V})] \div [R_{Ext} + 284 \ \Omega] \\ I_T &= 1.6 \ V/(R_{Ext} + 284) \end{split}$$

The timing equation becomes: $\Delta T = C_{Ext} \frac{1.9 \text{ V}}{I_T}$

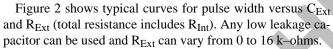
$$\begin{split} \Delta T &= [(C_{Ext})(1.9 \text{ V})] \div [1.6 \text{ V}/(R_{Ext} + 284)] \\ \Delta T &= C_{Ext} (R_{Ext} + 284) \ 1.19 \end{split}$$

where $\Delta T = Sec$

$$R_{Ext} = Ohms$$

 $C_{Ext} = Farads$

 $R_{Ext} = Ohms$



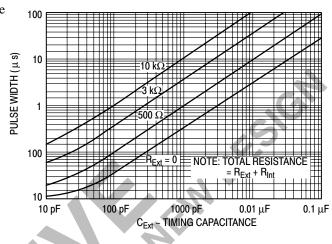
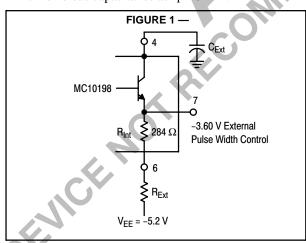


FIGURE 2 – TIMING PULSE WIDTH versus C_{Ext} and R_{Ext}

2. TRIGGERING —The \overline{E}_{pos} and \overline{E}_{Neg} inputs control the trigger input. The MC10198 can be programmed to trigger on the positive edge, negative edge, or both. Also, the trigger input can be totally disabled. The truth table is shown on the first page of the data sheet.

The device is totally retriggerable. However, as duty cycle approaches 100%, pulse width jitter can occur due to the recovery time of the circuit. Recovery time is basically dependent on capacitance C_{Ext}. Figure 3 shows typical recovery time versus capacitance at $I_T = 5$ mA.



10 μs 1 µs RECOVERY TIME 100 ns 10 ns 10 pF 100 pF 1000 pF $0.01 \mu F$ 0.1 μF CExt - TIMING CAPACITANCE

FIGURE 3 — RECOVERY TIME versus C_{Ext} @ I_T = 5 mA

3. HI-SPEED INPUT — This input is used for stretching very narrow pulses with minimum delay between the output pulse and the trigger pulse. The trigger input should be disabled when using the high-speed input. The MC10198 triggers on the rising edge, using this input, and input pulse width should narrow, typically less than 10 nanoseconds.

USAGE RULES:

- 1. Capacitor lead lengths should be kept very short to minimize ringing due to fast recovery rise times.
- 2. The \overline{E} inputs should <u>not</u> be tied to ground to establish a high logic level. A resistor divider or diode can be used to establish a -0.7 to -0.9 voltage level.
- 3. For optimum temperature stability; 0.5 mA is the best timing current I_T. The device is designed to have a constant voltage at the EXTERNAL PULSE WIDTH CONTROL over temperature at this current value.
- 4. Pulse Width modulation can be attained with the EXTERNAL PULSE WIDTH CONTROL. The timing current can be altered to vary the pulse width. Two schemes are:
 - a. The internal resistor is not used. A dependent current source is used to set the timing current as shown in Figure 4. A graph of pulse width versus timing current ($C_{Ext} = 13 \text{ pF}$) is shown in Figure 5.

b. A control voltage can also be used to vary the pulse width using an additional resistor (Figure 6). The current (I_T+I_C) is set by the voltage drop across $R_{Int}+R_{Ext}.$ The control current IC modifies I_T and alters the pulse width. Current I_C should never force I_T to zero. R_C typically $1\ k\Omega$

FIGURE 4 —

MC10198 — CExt

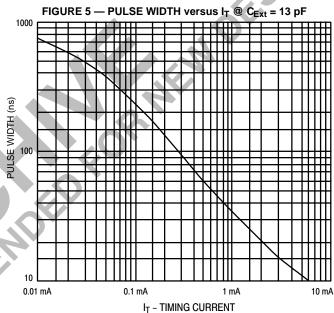
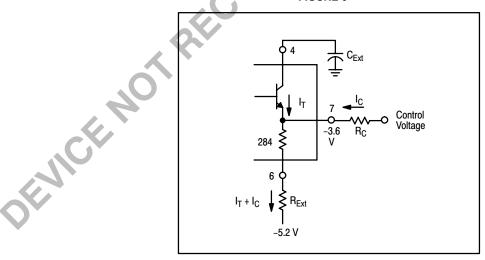
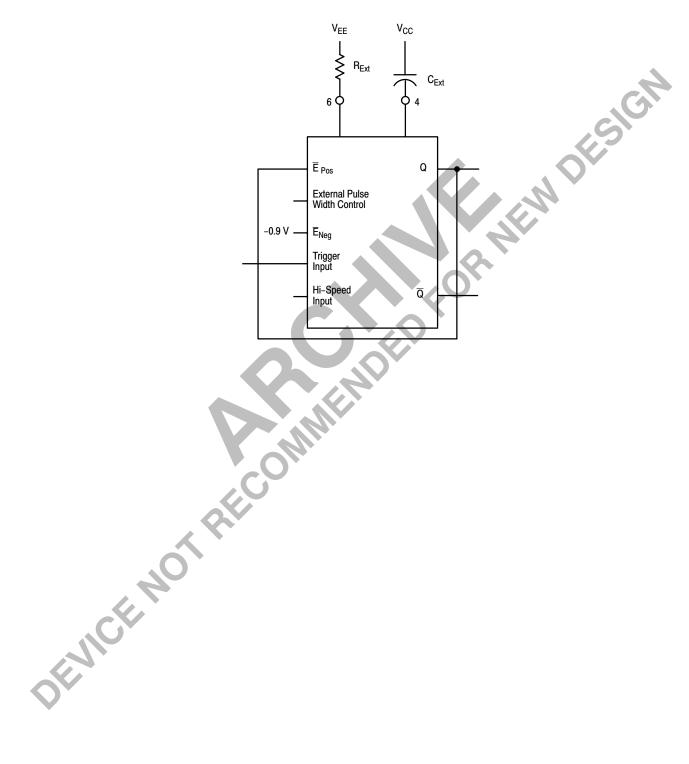


FIGURE 6 —



5. The MC10198 can be made non-retriggerable. The Q output is fed back to disable the trigger input during the triggered state (Logic Diagram). Figure 7 shows a positive triggered configuration; a similar configuration can be made for negative triggering.

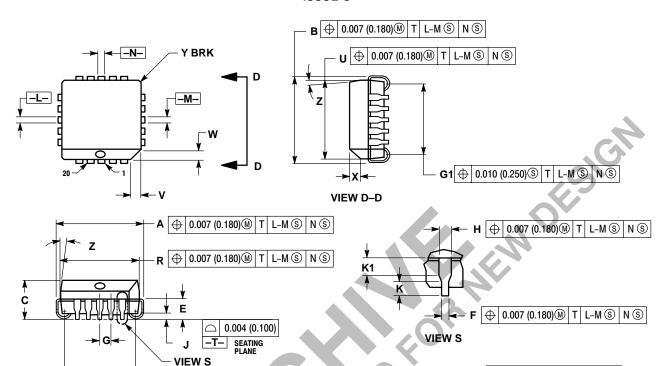
FIGURE 7 —



PACKAGE DIMENSIONS

PLCC-20 **FN SUFFIX**

PLASTIC PLCC PACKAGE CASE 775-02 ISSUE C



NOTES:

G1 ⊕ 0.010 (0.250)③ T L-M ⑤ N ⑤

- IOTES:

 1. DATUMS -L-, -M-, AND -N- DETERMINED WHERE TOP OF LEAD SHOULDER EXITS PLASTIC BODY AT MOLD PARTING LINE.

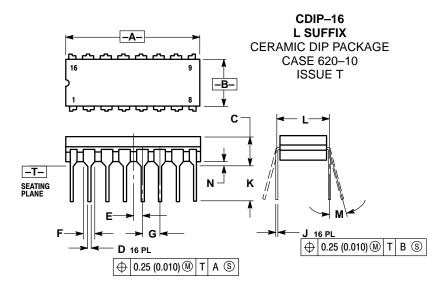
 2. DIMENSION G1, TRUE POSITION TO BE MEASURED AT DATUM -T-, SEATING PLANE.

 3. DIMENSIONS R AND U DO NOT INCLUDE MOLD FLASH. ALLOWABLE MOLD FLASH IS 0.010 (0.250) PER SIDE.

 4. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M. 1982.
- Y14.5M, 1982. CONTROLLING DIMENSION: INCH.
- THE PACKAGE TOP MAY BE SMALLER THAN THE PACKAGE BOTTOM BY UP TO 0.012 (0.300). DIMENSIONS R AND U ARE DETERMINED AT THE OUTERMOST EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.
- DIMENSION H DOES NOT INCLUDE DAMBAR PROTRUSION OR INTRUSION. THE DAMBAR PROTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE GREATER THAN 0.037 (0.940). THE DAMBAR INTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE SMALLER THAN 0.025 (0.635).

	INC	HES	MILLIM	ETERS
DIM	MIN	MAX	MIN	MAX
Α	0.385	0.395	9.78	10.03
В	0.385	0.395	9.78	10.03
С	0.165	0.180	4.20	4.57
E	0.090	0.110	2.29	2.79
F	0.013	0.019	0.33	0.48
G	0.050	BSC	1.27	BSC
Н	0.026	0.032	0.66	0.81
J	0.020		0.51	
K	0.025		0.64	
R	0.350	0.356	8.89	9.04
U	0.350	0.356	8.89	9.04
٧	0.042	0.048	1.07	1.21
W	0.042	0.048	1.07	1.21
X	0.042	0.056	1.07	1.42
Y		0.020		0.50
Z	2°	10°	2°	10 °
G1	0.310	0.330	7.88	8.38
K1	0.040		1.02	

PACKAGE DIMENSIONS



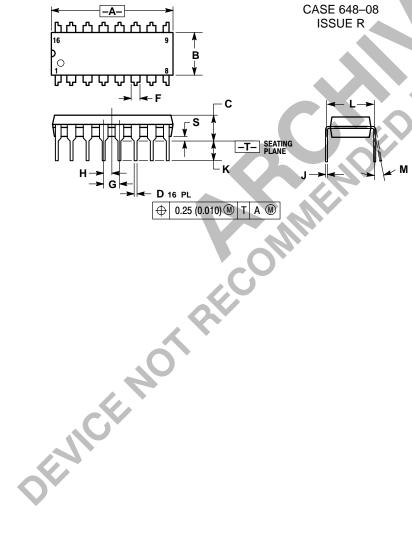
NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
 CONTROLLING DIMENSION: INCH.
 DIMENSION LTO CENTER OF LEAD WHEN CONTROLLING DIMENSION LTO CENTER OF LEAD WHEN

- FORMED PARALLEL
 DIMENSION F MAY NARROW TO 0.76 (0.030)
 WHERE THE LEAD ENTERS THE CERAMIC BODY.

	INC	HES	MILLIN	IETERS	
DIM	MIN	MAX	MIN	MAX	
Α	0.750	0.785	19.05	19.93	
В	0.240	0.295	6.10	7.49	
С		0.200		5.08	
D	0.015	0.020	0.39	0.50	
E	0.050	BSC	1.27 BSC		
F	0.055	0.065	1.40	1.65	
G	0.100	BSC	2.54 BSC		
Н	0.008	0.015	0.21	0.38	
K	0.125	0.170	3.18	4.31	
L	0.300	BSC	7.62	BSC	
М	0 °	15°	0 °	15°	
N	0.020	0.040	0.51	1.01	

PDIP-16 **P SUFFIX** PLASTIC DIP PACKAGE CASE 648-08 ISSUE R



- NOTES:
 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
 2. CONTROLLING DIMENSION: INCH.
 3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
 4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
 5. ROUNDED CORNERS OPTIONAL

	INC	HES	MILLIN	IETERS	
DIM	MIN	MIN MAX		MAX	
Α	0.740	0.770	18.80	19.55	
В	0.250	0.270	6.35	6.85	
C	0.145	0.175	3.69	4.44	
D	0.015	0.021	0.39	0.53	
F	0.040	0.70	1.02	1.77	
G	0.100	BSC	2.54 BSC		
Н	0.050	BSC	1.27	BSC	
J	0.008	0.015	0.21	0.38	
K	0.110	0.130	2.80	3.30	
L	0.295	0.305	7.50	7.74	
M	0°	10 °	0°	10 °	
S	0.020	0.040	0.51	1.01	



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