2.0% 5.0 V, 750 mA Low Dropout Linear Regulator with Delayed RESET

The CS8122 is a precision 5.0 V linear regulator capable of sourcing in excess of 750 mA. The $\overline{\text{RESET}}$'s delay time is externally programmed using a discrete RC network. During power up, or when the output goes out of regulation, the $\overline{\text{RESET}}$ lead remains in the low state for the duration of the delay. This function is independent of the input voltage and will function correctly as long as the output voltage remains at or above 1.0 V. Hysteresis is included in the Delay and the $\overline{\text{RESET}}$ comparators to improve noise immunity. A latching discharge circuit is used to discharge the delay capacitor when it is triggered by a brief fault condition.

The regulator is protected against a variety of fault conditions: i.e. reverse battery, overvoltage, short circuit and thermal runaway conditions. The regulator is protected against voltage transients ranging from –50 V to +40 V. Short circuit current is limited to 1.2 A (typ).

The CS8122 is an improved replacement for the CS8126 and features a tighter tolerance on its output voltage (2.0% vs. 4.0%).

The CS8122 is packaged in a 5 lead TO-220 with copper tab. The copper tab can be connected to a heat sink if necessary.

Features

- 5.0 V ±2.0% Regulated Output
- Low Dropout Voltage (0.6 V @ 0.5 A)
- 750 mA Output Current Capability
- Externally Programmed RESET Delay
- Fault Protection
 - Reverse Battery
 - 60 V Load Dump
 - -50 V Reverse Transient
 - Short Circuit
 - Thermal Shutdown
- Pb-Free Packages are Available*



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TO-220 FIVE LEAD T SUFFIX CASE 314D



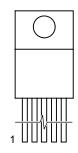
TO-220 FIVE LEAD TVA SUFFIX CASE 314K



TO-220 FIVE LEAD THA SUFFIX CASE 314A

PIN CONNECTIONS

TO-220 5-LEAD



Pin 1. V_{IN} 2.V_{OUT} 3. GND 4. Delay 5. RESET

DEVICE MARKING INFORMATION

See general marking information in the device marking section on page 2 of this data sheet.

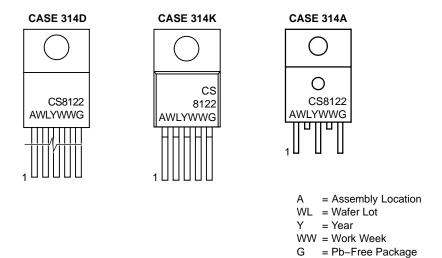
ORDERING INFORMATION

See detailed ordering and shipping information in the package dimensions section on page 8 of this data sheet.

^{*}For additional information on our Pb–Free strategy and soldering details, please download the ON Semiconductor Soldering and Mounting Techniques Reference Manual, SOLDERRM/D.

MARKING DIAGRAMS

TO-220 5-LEAD



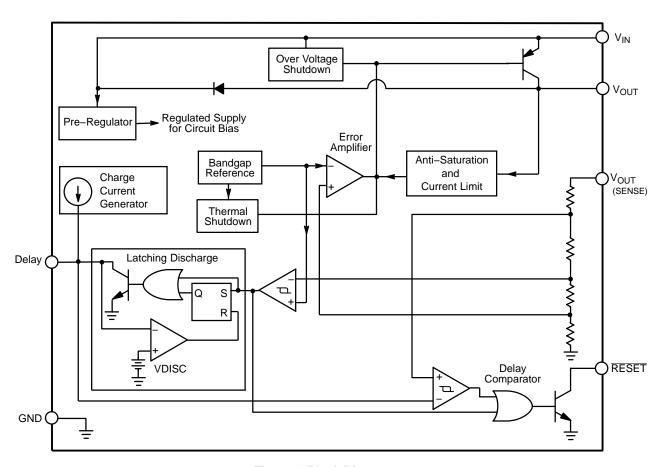


Figure 1. Block Diagram

ABSOLUTE MAXIMUM RATINGS

Rating	Value	Unit
Input Operating Range	-0.5 to 26	V
Power Dissipation	Internally Limited	-
Peak Transient Voltage (46 V Load Dump @ V _{IN} = 14 V)	-50, 60	V
Output Current	Internally Limited	-
Electrostatic Discharge (Human Body Model)	4.0	kV
Junction Temperature	-55 to +150	°C
Storage Temperature Range	-55 to +150	°C
Lead Temperature Soldering Wave Solder (through hole styles only) (Note 1)	260 peak	°C

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

$\textbf{ELECTRICAL CHARACTERISTICS} \quad (-40^{\circ}C \leq T_{A} \leq 125^{\circ}C, \ -40 \leq T_{J} \leq 150^{\circ}C, \ 6.0 \leq V_{IN} \leq 26 \ \text{V}, \ 5.0 \ \text{mA} \leq I_{OUT} \leq 500 \ \text{mA},$ $R_{RESET} = 4.7 \text{ k}\Omega$ to V_{CC} unless otherwise noted.) (Note 2)

Characteristic	Test Conditions	Min	Тур	Max	Unit	
OUTPUT STAGE (V _{OUT)}						
Output Voltage	-	4.9	5.0	5.1	V	
Dropout Voltage	I _{OUT} = 500 mA	_	0.35	0.60	V	
Supply Current	$I_{OUT} \le 10 \text{ mA}$ $I_{OUT} \le 100 \text{ mA}$ $I_{OUT} \le 500 \text{ mA}$	- - -	2.0 6.0 55	7.0 12 100	mA mA mA	
Line Regulation	6.0 V ≤ V _{IN} ≤ 26 V, I _{OUT} = 50 mA	_	5.0	50	mV	
Load Regulation	50 mA \leq I _{OUT} \leq 500 mA, V _{IN} = 14 V	_	10	50	mV	
Ripple Rejection	$f = 120 \text{ Hz}, 7.0 \le V_{IN} \le 17 \text{ V}, I_{OUT} = 250 \text{ mA}$	54	75	_	dB	
Current Limit	-	0.75	1.20	_	Α	
Overvoltage Shutdown	-	32	_	40	V	
Maximum Line Transient	V _{OUT} ≤ 5.5 V	60	95	_	V	
Reverse Polarity Input Voltage DC	V _{OUT} ≥ -0.6 V, 10 Ω Load	-15	-30	_	V	
Reverse Polarity Input Voltage Transient	1.0% Duty Cycle, T < 100 ms, 10 Ω Load	-50	-80	_	V	
Thermal Shutdown	Guaranteed by Design	150	180	210	°C	
RESET AND DELAY FUNCTIONS						
Delay Charge Current	V _{DELAY} = 2.0 V	5.0	10	15	μΑ	
RESET Threshold	V _{OUT} Increasing, V _{RT(ON)} V _{OUT} Decreasing, V _{RT(OFF)}	4.65 4.50	4.90 4.70	V _{OUT} – 0.01 V _{OUT} – 0.16	V V	
RESET Hysteresis	$V_{RH} = V_{RT(ON)} - V_{RT(OFF)}$	150	200	250	mV	
Delay Threshold	Charge, V _{DC(HI)} Discharge, V _{DC(L)}	3.25 2.85	3.50 3.10	3.75 3.35	V V	
Delay Hysteresis	-	200	400	800	mV	
RESET Output Voltage Low	1.0 V < V_{OUT} < $V_{RT(L)}$, 3.0 kΩ to V_{OUT}	_	0.1	0.4	V	
RESET Output Leakage	$V_{OUT} > V_{RT(H)}$	0	_	10	μΑ	
Delay Capacitor Discharge Voltage	Discharge Latched "ON", V _{OUT} > V _{RT}	_	0.2	0.5	V	
Delay Time	C _{DELAY} = 0.1 μF	16	32	48	ms	

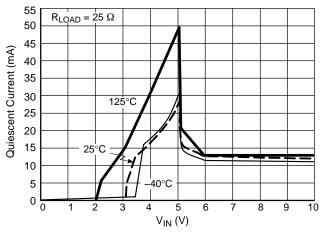
2. To observe safe operating junction temperatures, low duty cycle pulse testing is used in tests where applicable. Delay Time = $\frac{\text{CDelay} \times \text{VDelay Threshold Charge}}{\text{ICharge}} = \text{C}_{\text{Delay}} \times 3.5 \times 10^5 \text{ (typ)}$ **I**Charge

^{1. 10-}second maximum.

PACKAGE LEAD DESCRIPTION

PACKAGE LEAD # TO-220 5 LEAD	LEAD SYMBOL	FUNCTION
1	V _{IN}	Unregulated supply voltage to IC.
2	V _{OUT}	Regulated 5.0 V output.
3	GND	Ground Connection.
4	Delay	Timing capacitor for RESET function.
5	RESET	CMOS/TTL compatible output lead. RESET goes low whenever V _{OUT} drops below 6.0% of it's regulated value.

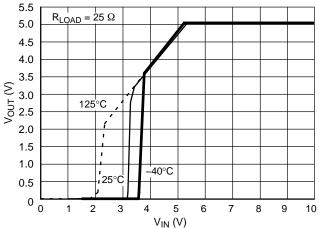
TYPICAL PERFORMANCE CHARACTERISTICS



120 Room Temp $R_{LOAD} = 6.67 \Omega$ 100 Quiescent Current. (mA) 80 60 $R_{LOAD} = 10 \Omega$ 40 20 $_{OAD} = NO LOAD$ 0 6 0 1 2 5 10 3 $V_{IN}(V)$

Figure 2. Quiescent Current vs. Input Voltage Over Temperature

Figure 3. Quiescent Current vs. Input Voltage Over Load Resistance





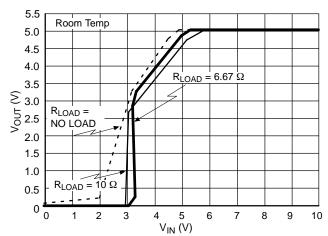
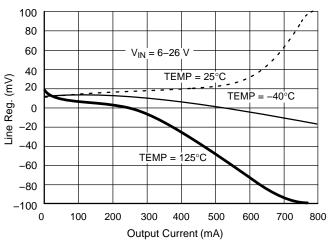


Figure 5. V_{OUT} vs. V_{IN} Over R_{LOAD}

TYPICAL PERFORMANCE CHARACTERISTICS



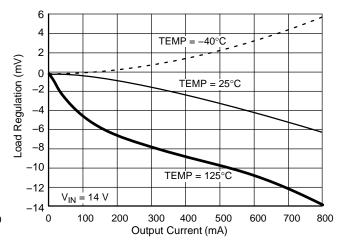


Figure 6. Line Regulation vs. Output Current

Figure 7. Load Regulation vs. Output Current

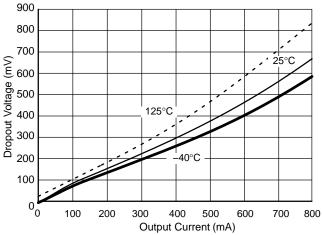


Figure 8. Dropout Voltage vs. Output Current

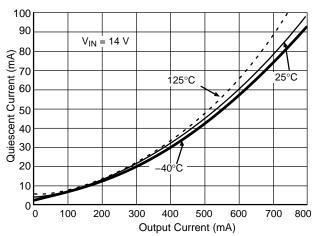


Figure 9. Quiescent Current vs. Output Current

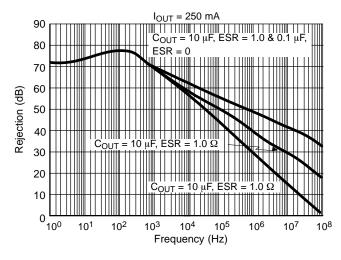


Figure 10. Ripple Rejection

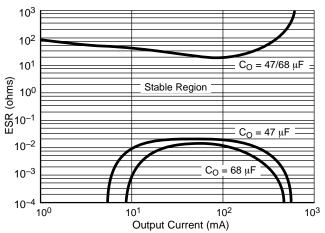


Figure 11. Output Capacitor ESR

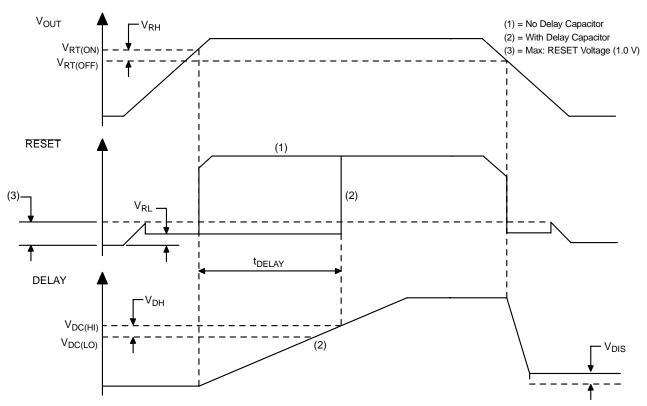


Figure 12. RESET Circuit Waveform

CIRCUIT DESCRIPTION

The CS8122 RESET function, has hysteresis on both the reset and delay comparators, a latching Delay capacitor discharge circuit, and operates down to 1.0 V.

The RESET circuit output is an open collector type with ON and OFF parameters as specified. The RESET output NPN transistor is controlled by the two circuits described (see Block Diagram on page 2).

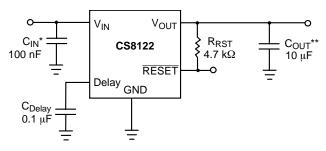
Low Voltage Inhibit Circuit

The Low Voltage Inhibit Circuit monitors output voltage, and when output voltage is below the specified minimum, causes the \overline{RESET} output transistor to be in the ON (saturation) state. When the output voltage is above the specified level, this circuit permits the \overline{RESET} output transistor to go into the OFF state if allowed by the \overline{RESET} Delay circuit.

Reset Delay Circuit

The Reset Delay Circuit provides a programmable (by external capacitor) delay on the \overline{RESET} output lead. The Delay lead provides source current to the external delay capacitor only when the Low Voltage Inhibit circuit indicates that output voltage is above $V_{RT(ON)}$. Otherwise, the Delay lead sinks current to ground (used to discharge the

delay capacitor). The discharge current is latched ON when the output voltage is below $V_{RT(OFF)}$. The Delay capacitor is fully discharged anytime the output voltage falls out of regulation, even for a short period of time. This feature ensures that a controlled \overline{RESET} pulse is generated following detection of an error condition. The circuit allows the \overline{RESET} output transistor to go to the OFF (open) state only when the voltage on the Delay lead is higher than $V_{DC(HI)}$.



*C_{IN} is required if regulator is far from the power source filter.

Figure 13. Test Circuit

 $^{**}C_{OUT}$ is required for stability.

APPLICATION NOTES

STABILITY CONSIDERATIONS

The output or compensation capacitor, C_{OUT}, helps determine three main characteristics of a linear regulator: start–up delay, load transient response and loop stability.

The capacitor value and type should be based on cost, availability, size and temperature constraints. A tantalum or aluminum electrolytic capacitor is best, since a film or ceramic capacitor with almost zero ESR can cause instability. The aluminum electrolytic capacitor is the least expensive solution, but, if the circuit operates at low temperatures (-25°C to -40°C), both the value and ESR of the capacitor will vary considerably. The capacitor manufacturers data sheet usually provides this information.

The value for the output capacitor C_{OUT} shown in Figure 13 should work for most applications, however it is not necessarily the optimized solution.

To determine an acceptable value for C_{OUT} for a particular application, start with a tantalum capacitor of the recommended value and work towards a less expensive alternative part.

- **Step 1:** Place the completed circuit with a tantalum capacitor of the recommended value in an environmental chamber at the lowest specified operating temperature and monitor the outputs with an oscilloscope. A decade box connected in series with the capacitor will simulate the higher ESR of an aluminum capacitor. Leave the decade box outside the chamber, the small resistance added by the longer leads is negligible.
- **Step 2:** With the input voltage at its maximum value, increase the load current slowly from zero to full load while observing the output for any oscillations. If no oscillations are observed, the capacitor is large enough to ensure a stable design under steady state conditions.
- **Step 3:** Increase the ESR of the capacitor from zero using the decade box and vary the load current until oscillations appear. Record the values of load current and ESR that cause the greatest oscillation. This represents the worst case load conditions for the regulator at low temperature.
- **Step 4:** Maintain the worst case load conditions set in step 3 and vary the input voltage until the oscillations increase. This point represents the worst case input voltage conditions.
- **Step 5:** If the capacitor is adequate, repeat steps 3 and 4 with the next smaller valued capacitor. A smaller capacitor will usually cost less and occupy less board space. If the output oscillates within the range of expected operating conditions, repeat steps 3 and 4 with the next larger standard capacitor value.
- **Step 6:** Test the load transient response by switching in various loads at several frequencies to simulate its real working environment. Vary the ESR to reduce ringing.
- **Step 7:** Raise the temperature to the highest specified operating temperature. Vary the load current as instructed in step 5 to test for any oscillations.

Once the minimum capacitor value with the maximum ESR is found, a safety factor should be added to allow for the tolerance of the capacitor and any variations in regulator performance. Most good quality aluminum electrolytic capacitors have a tolerance of \pm 20% so the minimum value found should be increased by at least 50% to allow for this tolerance plus the variation which will occur at low temperatures. The ESR of the capacitor should be less than 50% of the maximum allowable ESR found in step 3 above.

CALCULATING POWER DISSIPATION IN A SINGLE OUTPUT LINEAR REGULATOR

The maximum power dissipation for a single output regulator (Figure 14) is:

$$P_{D(max)} = \{V_{IN(max)} - V_{OUT(min)}\}I_{OUT(max)} + V_{IN(max)}I_{Q}$$
 (1)

where

V_{IN(max)} is the maximum input voltage,

V_{OUT(min)} is the minimum output voltage,

 $I_{OUT(max)}$ is the maximum output current for the application, and

 I_Q is the quiescent current the regulator consumes at $I_{OUT(max)}. \label{eq:lower}$

Once the value of $P_{D(max)}$ is known, the maximum permissible value of $R_{\theta JA}$ can be calculated:

$$R_{\theta}JA = \frac{150^{\circ}C - T_{A}}{P_{D}}$$
 (2)

The value of $R_{\theta JA}$ can then be compared with those in the package section of the data sheet. Those packages with $R_{\theta JA}$'s less than the calculated value in equation 2 will keep the die temperature below 150°C.

In some cases, none of the packages will be sufficient to dissipate the heat generated by the IC, and an external heatsink will be required.

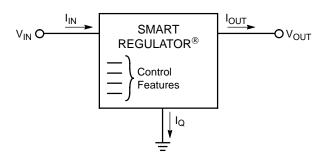


Figure 14. Single Output Regulator With Key Performance Parameters Labeled

HEAT SINKS

A heat sink effectively increases the surface area of the package to improve the flow of heat away from the IC and into the surrounding air.

Each material in the heat flow path between the IC and the outside environment will have a thermal resistance. Like series electrical resistances, these resistances are summed to determine the value of $R_{\theta \rm JA}$.

$$R_{\theta}JA = R_{\theta}JC + R_{\theta}CS + R_{\theta}SA \tag{3}$$

where:

 $R_{\theta JC}$ = the junction-to-case thermal resistance,

 $R_{\theta CS}$ = the case-to-heatsink thermal resistance, and

 $R_{\theta SA}$ = the heatsink-to-ambient thermal resistance.

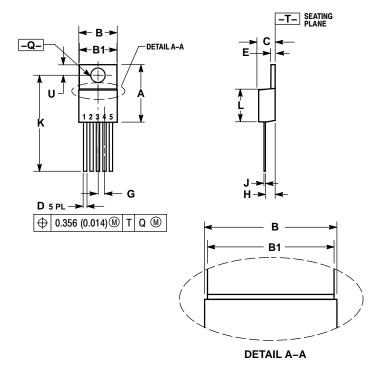
 $R_{\theta JC}$ appears in the package section of the data sheet. Like $R_{\theta JA}$, it too is a function of package type. $R_{\theta CS}$ and $R_{\theta SA}$ are functions of the package type, heatsink and the interface between them. These values appear in heat sink data sheets of heat sink manufacturers.

ORDERING INFORMATION

Device	Package	Shipping
CS8122YT5	TO-220 STRAIGHT	
CS8122YT5G	TO-220 STRAIGHT (Pb-Free)	
CS8122YTVA5	TO-220 VERTICAL	
CS8122YTVA5G	TO-220 VERTICAL (Pb-Free)	50 Units / Rail
CS8122YTHA5	TO-220 HORIZONTAL	
CS8122YTHA5G	TO-220 HORIZONTAL (Pb-Free)	

PACKAGE DIMENSIONS

TO-220 CASE 314D-04 ISSUE F



NOTES:

- IOTES:

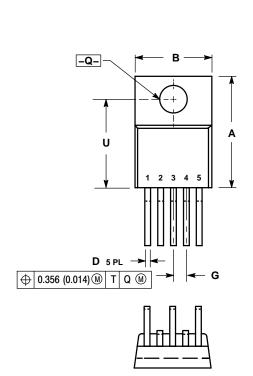
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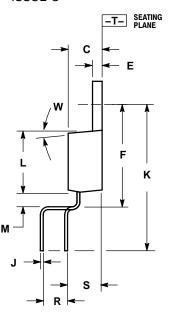
 2. CONTROLLING DIMENSION: INCH.

 3. DIMENSION DOES NOT INCLUDE INTERCONNECT BAR (DAMBAR) PROTRUSION. DIMENSION D INCLUDING PROTRUSION SHALL NOT EXCEED 10.92 (0.043) MAXIMUM.

	INCHES		MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.572	0.613	14.529	15.570
В	0.390	0.415	9.906	10.541
B1	0.375	0.415	9.525	10.541
C	0.170	0.180	4.318	4.572
D	0.025	0.038	0.635	0.965
Е	0.048	0.055	1.219	1.397
G	0.067 BSC		1.702 BSC	
Н	0.087	0.112	2.210	2.845
J	0.015	0.025	0.381	0.635
K	0.977	1.045	24.810	26.543
L	0.320	0.365	8.128	9.271
Q	0.140	0.153	3.556	3.886
U	0.105	0.117	2.667	2 972

TO-220 **TVA SUFFIX** CASE 314K-01 ISSUE O





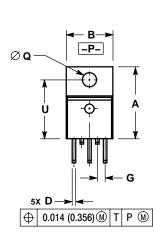
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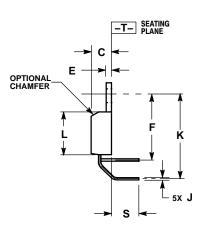
- DIMENSIONING AND TOLERANCING PER ANSI
- DIMENSIONING AND TOLEHANCING PEH ANS Y14.5M, 1982.
 CONTROLLING DIMENSION: INCH.
 DIMENSION D DOES NOT INCLUDE INTERCONNECT BAR (DAMBAR) PROTRUSION. DIMENSION D INCLUDING PROTRUSION SHALL NOT EXCEED 10.92 (0.043) MAXIMUM.

	INCHES		MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.560	0.590	14.22	14.99
В	0.385	0.415	9.78	10.54
С	0.160	0.190	4.06	4.83
D	0.027	0.037	0.69	0.94
E	0.045	0.055	1.14	1.40
F	0.530	0.545	13.46	13.84
G	0.067 BSC		1.70 BSC	
J	0.014	0.022	0.36	0.56
K	0.785	0.800	19.94	20.32
L	0.321	0.337	8.15	8.56
M	0.063	0.078	1.60	1.98
Q	0.146	0.156	3.71	3.96
R	0.271	0.321	6.88	8.15
S	0.146	0.196	3.71	4.98
U	0.460	0.475	11.68	12.07
W	5°		5	i °

PACKAGE DIMENSIONS

TO-220 **THA SUFFIX** CASE 314A-03 ISSUE E





- 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
 2. CONTROLLING DIMENSION: INCH.
- 3. DIMENSION D DOES NOT INCLUDE
 INTERCONNECT BAR (DAMBAR) PROTRUSION.
 DIMENSION D INCLUDING PROTRUSION SHALL NOT EXCEED 0.043 (1.092) MAXIMUM.

	INCHES		MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.572	0.613	14.529	15.570
В	0.390	0.415	9.906	10.541
С	0.170	0.180	4.318	4.572
D	0.025	0.038	0.635	0.965
E	0.048	0.055	1.219	1.397
F	0.570	0.585	14.478	14.859
G	0.067 BSC		1.702 BSC	
J	0.015	0.025	0.381	0.635
K	0.730	0.745	18.542	18.923
L	0.320	0.365	8.128	9.271
Q	0.140	0.153	3.556	3.886
S	0.210	0.260	5.334	6.604
U	0.468	0.505	11.888	12.827

PACKAGE THERMAL DATA

Parar	meter	TO-220 FIVE LEAD	Unit
$R_{ heta JC}$	Typical	2.1	°C/W
$R_{\theta JA}$	Typical	50	°C/W

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