MC100EP16VS

3.3V / 5V ECL Differential Receiver/Driver with Variable Output Swing

The MC100EP16VS is a differential receiver with variable output amplitude. The device is functionally equivalent to the 100EP16 with an input pin that controls the amplitude of the outputs.

The V_{CTRL} input pin controls the output amplitude of the EP16VS and is referenced to V_{CC}. (See Figure 4.) The operational range of the V_{CTRL} input is from $\leq V_{BB}$ (max output amplitude) to V_{CC} (min output amplitude). (See Figure 3.) A variable resistor between the V_{CC} and V_{BB} pins, with the wiper driving V_{CTRL}, can control the output amplitude. Typical application circuits and a V_{CTRL} Voltage vs. Output Amplitude graph are described in this data sheet. When left open, the V_{CTRL} pin will be internally pulled down to V_{EE} and operate as a standard EP16, with 100% output amplitude.

The V_{BB} pin, an internally generated voltage supply, is available to this device only. For single−ended input conditions, the unused differential input is connected to V_{BB} as a switching reference voltage. V_{BB} may also rebias AC coupled inputs. When used, decouple V_{BB} and V_{CC} via a 0.01 µF capacitor and limit current sourcing or sinking to 0.5 mA. When not used, V_{BB} should be left open.
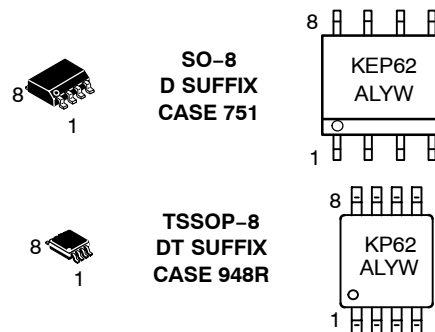
- 220 ps Propagation Delay
- Maximum Frequency > 4 GHz Typical (See Graph)
- The 100 Series Contains Temperature Compensation
- PECL Mode Operating Range: V_{CC} = 3.0 V to 5.5 V with V_{EE} = 0 V
- NECL Mode Operating Range: V_{CC} = 0 V with V_{EE} = −3.0 V to −5.5 V
- Open Input Default State
- Q Output Will Default LOW with Inputs Open or at V_{EE}

ON Semiconductor®

http://onsemi.com

ORDERING INFORMATION

Device	Package	Shipping
MC100EP16VSD	SO−8	98 Units/Rail
MC100EP16VSDR2	SO−8	2500 Tape & Reel
MC100EP16VSDT	TSSOP	100 Units/Rail
MC100EP16VSDTR2	TSSOP	2500 Tape & Reel

MC100EP16VS
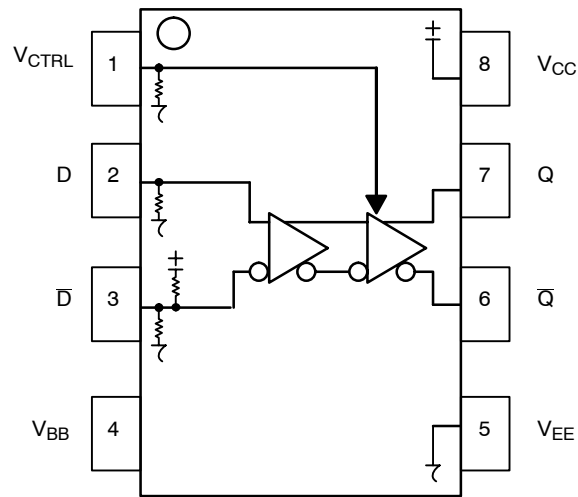
Figure 1. 8−Lead Pinout (Top View) **and Logic Diagram**

PIN DESCRIPTION

PIN	FUNCTION	
D*, $\overline{D}$**	ECL Data Inputs	2, 3
Q, $\overline{Q}$	ECL Data Outputs	6, 7
V_{CTRL}*	Output Swing Control	1
V_{BB}	Reference Voltage Output	4
V_{CC}	Positive Supply	8
V_{EE}	Negative Supply	5
NC	No Connect	

* Pins will default LOW when left open.

** Pins will default to $V_{CC}/2$ when left open.

ATTRIBUTES

Characteristics		Value
Internal Input Pulldown Resistor		75 kΩ
Internal Input Pullup Resistor		37.5 kΩ
ESD Protection	Human Body Model Machine Model Charged Device Model	> 4 kV > 200 V > 2 kV
Moisture Sensitivity, Indefinite Time Out of Drypack (Note 1)		Level 1
Flammability Rating	Oxygen Index: 28 to 34	UL−94 code V−0 A 1/8″
Transistor Count		140 Devices
Meets or exceeds JEDEC Spec EIA/JESD78 IC Latchup Test		

1. For additional information, see Application Note AND8003/D.

MAXIMUM RATINGS (Note 2)

Symbol	Parameter	Condition 1	Condition 2	Rating	Units
V_{CC}	PECL Mode Power Supply	V_{EE} = 0 V		6	V
V_{EE}	NECL Mode Power Supply	V_{CC} = 0 V		−6	V
V_I	PECL Mode Input Voltage NECL Mode Input Voltage	V_{EE} = 0 V V_{CC} = 0 V	$V_I \leq V_{CC}$ $V_I \geq V_{EE}$	6 −6	V V
I_{out}	Output Current	Continuous Surge		50 100	mA mA
I_{BB}	V_{BB} Sink/Source			± 0.5	mA
TA	Operating Temperature Range			−40 to +85	°C
T_{stg}	Storage Temperature Range			−65 to +150	°C
θ_{JA}	Thermal Resistance (Junction−to−Ambient)	0 LFPM 500 LFPM	8 SOIC 8 SOIC	190 130	°C/W °C/W
θ_{JC}	Thermal Resistance (Junction−to−Case)	std bd	8 SOIC	41 to 44	°C/W
θ_{JA}	Thermal Resistance (Junction−to−Ambient)	0 LFPM 500 LFPM	8 TSSOP 8 TSSOP	185 140	°C/W °C/W
θ_{JC}	Thermal Resistance (Junction−to−Case)	Standard Board	8 TSSOP	41 to 44 ± 5%	°C/W
T_{sol}	Wave Solder	< 2 to 3 sec @ 248°C		265	°C

2. Maximum Ratings are those values beyond which device damage may occur.

DC CHARACTERISTICS, PECL V_{CC} = 3.3 V, V_{EE} = 0 V (Note 3)

Symbol	Characteristic	−40°C			25°C			85°C			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
I_{EE}	Power Supply Current	30	36	42	31	38	44	32	40	48	mA
V_{OH}	Output HIGH Voltage (Max Swing) (Note 4) $V_{CC} \geq V_{CTRL} \geq V_{EE}$	2155		2405	2155		2405	2155		2405	mV
V_{OL}	Output LOW Voltage (Max Swing) (Note 4) $V_{CTRL} \leq V_{BB}$	1355	1490	1605	1355	1520	1605	1355	1520	1605	mV
	$VCC \geq V_{CTRL} > V_{BB}$		See Fig.2			See Fig.2			See Fig.2		
	$V_{CTRL} = V_{CC}$ (Min Swing)	2105	2230	2355	2095	2220	2345	2065	2190	2315	
V_{IH}	D, $\overline{D}$ Input HIGH Voltage (Single−Ended)	2075		2420	2075		2420	2075		2420	mV
V_{IL}	D, $\overline{D}$ Input LOW Voltage (Single−Ended)	1490		1675	1490		1675	1490		1675	mV
V_{BB}	Output Voltage Reference	1805	1905	2005	1805	1905	2005	1805	1905	2005	mV
V_{CTRL}	Input Voltage (V_{CTRL})	V_{EE}		V_{CC}	V_{EE}		V_{CC}	V_{EE}		V_{CC}	mV
V_{IHCMR}	Input HIGH Voltage Common Mode Range (Differential) (Note 5)	2.0		2.9	2.0		2.9	2.0		2.9	V
I_{IH}	Input HIGH Current			150			150			150	µA
I_{IL}	Input LOW Current D $\overline{D}$	0.5 −150			0.5 −150			0.5 −150			µA

NOTE: EP circuits are designed to meet the DC specifications shown in the above table after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse airflow greater than 500 lfpm is maintained.

3. Input and output parameters vary 1:1 with V_{CC}. V_{EE} can vary +0.3 V to −2.2 V.
4. All loading with 50 Ω to V_{CC}−2.0 volts. V_{OH} does not change with V_{CTRL}. V_{OL} changes with V_{CTRL}. V_{CTRL} is referenced to V_{CC}.
5. V_{IHCMR} min varies 1:1 with V_{EE}, V_{IHCMR} max varies 1:1 with V_{CC}. The V_{IHCMR} range is referenced to the most positive side of the differential input signal.

DC CHARACTERISTICS, PECL V_{CC} = 5.0 V, V_{EE} = 0 V (Note 6)

Symbol	Characteristic	−40°C			25°C			85°C			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
I_{EE}	Power Supply Current	30	36	42	31	38	44	32	40	48	mA
V_{OH}	Output HIGH Voltage (Note 7) $V_{CC} > V_{CTRL} > V_{EE}$	3855	3980	4105	3855	3980	4105	3855	3980	4105	mV
V_{OL}	Output LOW Voltage (Max Swing) (Note 7) $V_{CTRL} \leq V_{BB}$	3055	3190	3305	3055	3220	3305	3055	3220	3305	mV
	$VCC \geq V_{CTRL} > V_{BB}$		See Fig.2			See Fig.2			See Fig.2		
	$V_{CTRL} = V_{CC}$ (Min Swing)	3805	3930	4055	3795	3920	4045	3765	3890	4015	
V_{IH}	D, $\overline{D}$ Input HIGH Voltage (Single−Ended)	3775		4120	3775		4120	3775		4120	mV
V_{IL}	D, $\overline{D}$ Input LOW Voltage (Single−Ended)	3190		3375	3190		3375	3190		3375	mV
V_{CTRL}	Input Voltage (V_{CTRL})	V_{EE}		V_{CC}	V_{EE}		V_{CC}	V_{EE}		V_{CC}	mV
V_{BB}	Output Voltage Reference	3505	3605	3705	3505	3605	3705	3505	3605	3705	mV
V_{IHCMR}	Input HIGH Voltage Common Mode Range (Differential) (Note 8)	2.0		4.6	2.0		4.6	2.0		4.6	V
I_{IH}	Input HIGH Current			150			150			150	µA
I_{IL}	Input LOW Current D $\overline{D}$	0.5 −150			0.5 −150			0.5 −150			µA

NOTE: EP circuits are designed to meet the DC specifications shown in the above table after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse airflow greater than 500 lfpm is maintained.
6. Input and output parameters vary 1:1 with V_{CC}. V_{EE} can vary +2.0 V to −0.5 V.
7. All loading with 50 Ω to V_{CC}−2.0 volts. V_{OH} does not change with V_{CTRL}. V_{OL} changes with V_{CTRL}. V_{CTRL} is referenced to V_{CC}.
8. V_{IHCMR} min varies 1:1 with V_{EE}, V_{IHCMR} max varies 1:1 with V_{CC}. The V_{IHCMR} range is referenced to the most positive side of the differential input signal.

DC CHARACTERISTICS, NECL V_{CC} = 0 V; V_{EE} = −5.5 V to −3.0 V (Note 9)

Symbol	Characteristic	−40°C			25°C			85°C			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
I_{EE}	Power Supply Current	30	36	42	31	38	44	32	40	48	mA
V_{OH}	Output HIGH Voltage (Note 10) $V_{CC} > V_{CTRL} > V_{EE}$	−1145	−1020	−895	−1145	−1020	−895	−1145	−1020	−895	mV
V_{OL}	Output LOW Voltage (Max Swing) (Note 10) $V_{CTRL} \leq V_{BB}$	−1945	−1810	−1695	−1945	−1780	−1695	−1945	−1780	−1695	mV
	$VCC \geq V_{CTRL} > V_{BB}$		See Fig.2			See Fig.2			See Fig.2		
	$V_{CTRL} = V_{CC}$ (Min Swing)	−1195	−1070	−945	−1205	−1080	−955	−1235	−1110	−985	
V_{IH}	D, $\overline{D}$ Input HIGH Voltage (Single−Ended)	−1225		−880	−1225		−880	−1225		−880	mV
V_{IL}	D, $\overline{D}$ Input LOW Voltage (Single−Ended)	−1810		−1625	−1810		−1625	−1810		−1625	mV
V_{BB}	Output Voltage Reference	−1525	−1425	−1325	−1525	−1425	−1325	−1525	−1425	−1325	mV
V_{CTRL}	Input Voltage (V_{CTRL})	V_{EE}		V_{CC}	V_{EE}		V_{CC}	V_{EE}		V_{CC}	mV
V_{IHCMR}	Input HIGH Voltage Common Mode Range (Differential) (Note 11)	V_{EE}+2.0		−0.4	V_{EE}+2.0		−0.4	V_{EE}+2.0		−0.4	V
I_{IH}	Input HIGH Current			150			150			150	µA
I_{IL}	Input LOW Current D $\overline{D}$	0.5 −150			0.5 −150			0.5 −150			µA

NOTE: EP circuits are designed to meet the DC specifications shown in the above table after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse airflow greater than 500 lfpm is maintained.
9. Input and output parameters vary 1:1 with V_{CC}.
10. All loading with 50 Ω to V_{CC}−2.0 volts. V_{OH} does not change with V_{CTRL}. V_{OL} changes with V_{CTRL}. V_{CTRL} is referenced to V_{CC}.
11. V_{IHCMR} min varies 1:1 with V_{EE}, V_{IHCMR} max varies 1:1 with V_{CC}. The V_{IHCMR} range is referenced to the most positive side of the differential input signal.

MC100EP16VS

AC CHARACTERISTICS V_{CC} = 0 V; V_{EE} = −3.0 V to −5.5 V or V_{CC} = 3.0 V to 5.5 V; V_{EE} = 0 V (Note 12)

Symbol	Characteristic		−40°C			25°C			85°C			Unit
			Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
f_{max}	Maximum Toggle Frequency (See Figure 6. F_{max}/JITTER)			> 4			> 4			> 4		GHz
t_{PLH}, t_{PHL}	Propagation Delay to Output Differential	Max Swing	150	220	280	150	220	280	160	240	300	ps
		Min Swing	90	150	210	90	150	210	100	160	220	
t_{SKEW}	Duty Cycle Skew (Note 13)			5.0	20		5.0	20		5.0	20	ps
t_{JITTER}	Cycle−to−Cycle Jitter (See Figure 6. F_{max}/JITTER)			0.2	< 1		0.2	< 1		0.2	< 1	ps
V_{PP}	Input Voltage Swing (Differential) (Note 14)		150	800	1200	150	800	1200	150	800	1200	mV
t_r	Output Rise/Fall Times	Max Swing Q	70	120	170	80	130	180	100	150	200	ps
t_f	(20% − 80%)	Min Swing	30	80	130	20	70	120	20	70	120	

12. Measured using a 750 mV source, 50% duty cycle clock source. All loading with 50 Ω to V_{CC}−2.0 V.
13. Skew is measured between outputs under identical transitions. Duty cycle skew is defined only for differential operation when the delays are measured from the cross point of the inputs to the cross point of the outputs.
14. V_{PP}(min) is minimum input swing for which AC parameters are guaranteed.

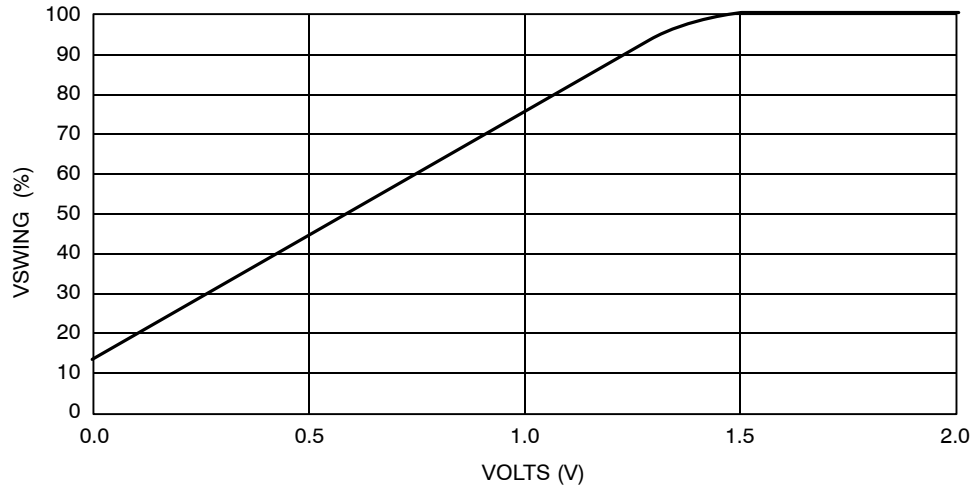**Figure 2. V_{CC} − V_{CTRL} (pin #1)**

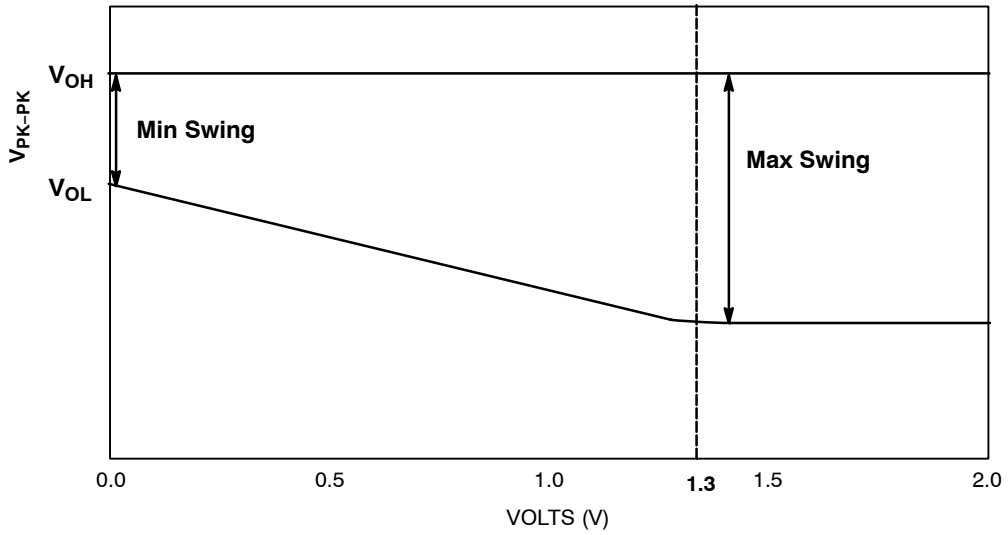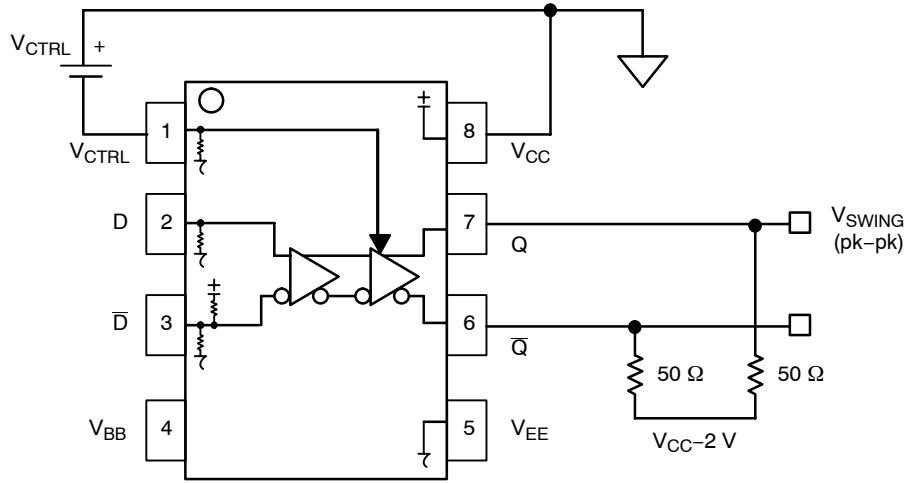**Figure 3. $V_{CC} - V_{CTRL}$**

Figure 4. Voltage Source Implementation
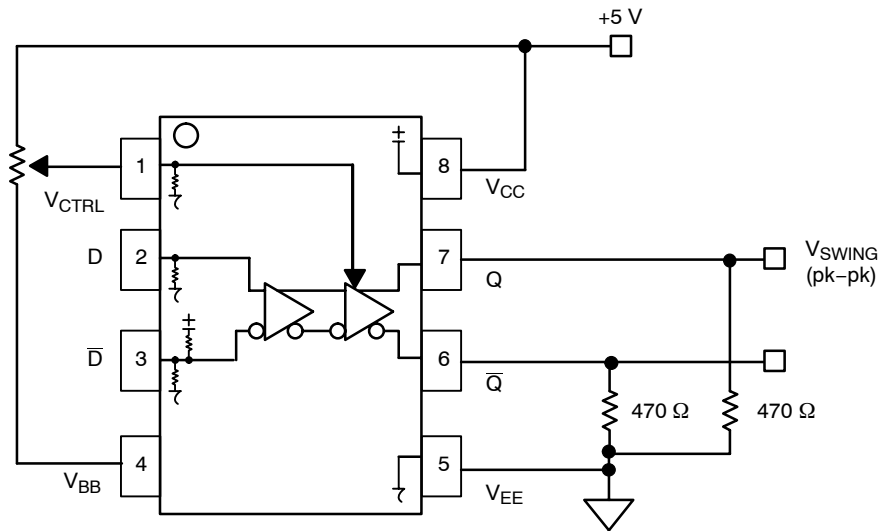
Figure 5. Alternative Implementation
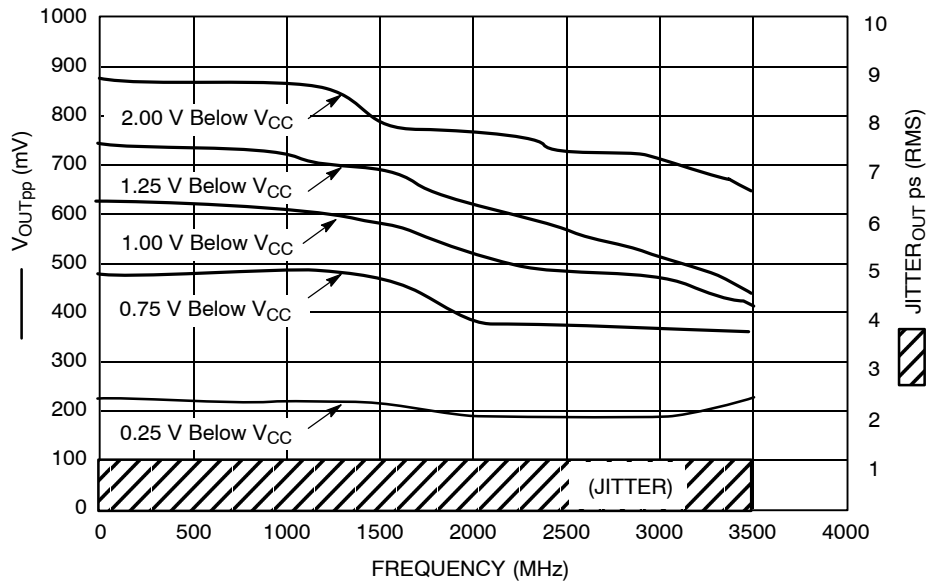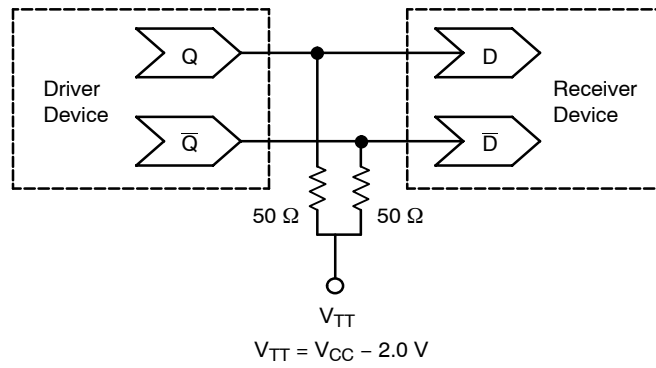

Figure 6. F$_{max}$/Jitter

MC100EP16VS

$V_{TT} = V_{CC} - 2.0 \text{ V}$

**Figure 7. Typical Termination for Output Driver and Device Evaluation
(See Application Note AND8020 – Termination of ECL Logic Devices.)**