

## GENERAL DESCRIPTION

The IDTF2255 is a low insertion loss **Voltage Variable RF Attenuator (VVA)** designed for a multitude of wireless and other RF applications. This device covers a broad frequency range from 1MHz to 3000MHz. In addition to providing low insertion loss, the IDTF2255 provides excellent linearity performance over its entire voltage control and attenuation range.

The F2255 uses a single positive supply voltage of 3.15V to 5.25V. Other features include the  $V_{MODE}$  pin allowing either positive or negative voltage control slope vs attenuation and multi-directional operation meaning the RF input can be applied to either RF1 or RF2 pins. Control voltage ranges from 0V to 3.6V using either positive or negative control voltage slope.

## COMPETITIVE ADVANTAGE

IDTF2255 provides extremely low insertion loss and superb IP3, IP2, Return Loss and Slope Linearity across the control range. Comparing to competitive VVAs this device is better as follows:

- ✓ Operation down to 1MHz
- ✓ Insertion Loss @ 500MHz: 1.1dB
- ✓ Maximum Attenuation Slope: 33dB/Volt
- ✓ Minimum Output IP3: 35dBm
- ✓ Minimum Input IP2: 74dBm
- ✓ High Operating Temperature: +105°C

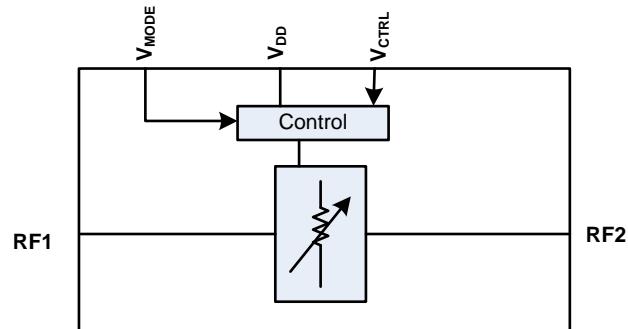
## APPLICATIONS

- Base Station 2G, 3G, 4G
- Portable Wireless
- Repeaters and E911 systems
- Digital Pre-Distortion
- Point to Point Infrastructure
- Public Safety Infrastructure
- Satellite Receivers and Modems
- WIMAX Receivers and Transmitters
- Military Radios covering HF, VHF, UHF
- RFID handheld and portable readers
- Cable Infrastructure
- Wireless LAN
- Test / ATE Equipment

## FEATURES

- Low Insertion Loss: 1.1dB @ 500MHz
- Typical / Min IIP3: 60dBm / 46dBm
- Typical / Min IIP2: 98dBm / 74dBm
- 33dB Attenuation Range
- Bi-directional RF ports
- +36dBm Input P1dB compression
- $V_{MODE}$  pin allows either positive or negative control response
- Linear-in-dB attenuation characteristic
- Supply voltage: 3.15V to 5.25V
- $V_{CTRL}$  range: 0V to 3.6V using 5V supply
- +105°C max operating temperature
- 3mm x 3mm, 16-pin QFN package

## DEVICE BLOCK DIAGRAM



## ORDERING INFORMATION

**IDTF2255NLGK8**

Annotations for ordering:  
 Omit IDT prefix  
 0.9 mm height package  
 Tape & Reel  
 RF product Line  
 Green

## PART# MATRIX

Part#	RF Freq Range (MHz)	Insertion Loss (dB)	IIP3 (dBm)	Pinout Compatibility
F2250	50 - 6000	1.4 (at 2GHz)	+65	RFMD
<b>F2255</b>	<b>1 - 3000</b>	<b>1.1 (at 500MHz)</b>	<b>+60</b>	
F2258	50 - 6000	1.4 (at 2GHz)	+65	Hittite

## ABSOLUTE MAXIMUM RATINGS

Parameter / Condition	Symbol	Min	Max	Units
$V_{DD}$ to GND	$V_{DD}$	-0.3	5.5	V
$V_{MODE}$ to GND	$V_{MODE}$	-0.3	Minimum ( $V_{DD}$ , 3.9 )	V
$V_{CTRL}$ to GND	$V_{CTRL}$	-0.3	Minimum ( $V_{DD}$ , 4.0 )	V
RF1, RF2 to GND	$V_{RF}$	-0.3	0.3	V
RF1 or RF2 Input Power applied for 24 hours maximum ( $V_{DD}$ applied @ 2GHz and $T_c=+85^\circ\text{C}$ )	$P_{MAX24}$		30	dBm
RF1 or RF2 Continuous Operating Power	$P_{MAX\_OP}$		See Figure 1	dBm
Maximum Junction Temperature	$T_{JMAX}$		+150	°C
Storage Temperature Range	$T_{ST}$	-65	+150	°C
Lead Temperature (soldering, 10s)	$T_{LEAD}$		+260	°C
ESD Voltage– HBM (Per ESD STM5.1-2007)	$V_{ESDHBM}$		Class 2	
ESD Voltage – CDM (Per ESD STM5.3.1-2009)	$V_{ESDCDM}$		Class C3	

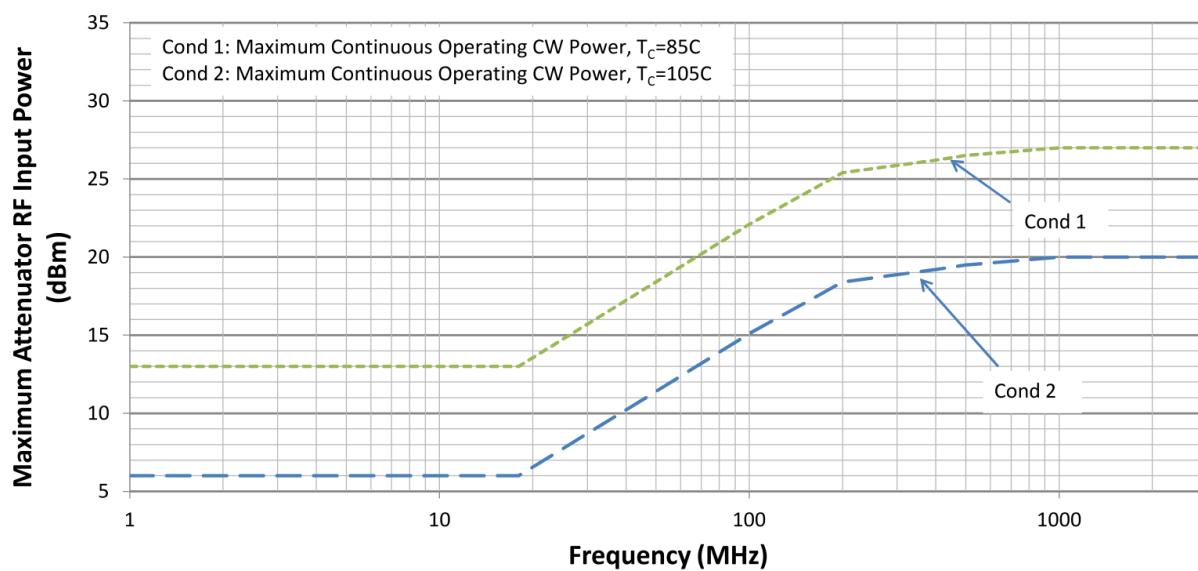


FIGURE 1: MAXIMUM OPERATING RF INPUT POWERS VS. RF FREQUENCY

Stresses above those listed above may cause permanent damage to the device. Functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## PACKAGE THERMAL AND MOISTURE CHARACTERISTICS

$\Theta_{JA}$ (Junction – Ambient)	80.6°C/W
$\Theta_{JC}$ (Junction – Case) The Case is defined as the exposed paddle	5.1°C/W
Moisture Sensitivity Rating (Per J-STD-020)	MSL 1

## IDTF2255 OPERATING CONDITIONS

Parameter	Symbol	Condition	Min	Typ	Max	Units
Operating Frequency Range	$F_{RF}$		1		3000	MHz
Supply Voltage	$V_{DD}$		3.15		5.25	V
V <sub>MODE</sub> Logic	$V_{IH}$	$V_{DD} > 3.9V$	1.17		3.6 <sup>2</sup>	V
		$V_{DD} = 3.15$ to 3.9V	1.17		$V_{DD} - 0.3V$	
	$V_{IL}$		0		0.63	
V <sub>CTRL</sub> Range	$V_{CTRL}$	$V_{DD} = 3.9V$ to 5.25V	0		3.6	V
		$V_{DD} = 3.15V$ to 3.9V	0		$V_{DD} - 0.3$	
Supply Current	$I_{DD}$		<b>0.50</b> <sup>1</sup>	1.15	<b>2</b>	mA
Logic Current	$I_{MODE}$		<b>-1.0</b>		<b>38</b>	$\mu A$
$I_{CTRL}$ Current	$I_{CTRL}$		<b>-1.0</b>		<b>14</b>	$\mu A$
RF Operating Power <sup>3</sup>	$P_{MAXCW}$				See Figure 1	dBm
RF1 Port Impedance	$Z_{RF1}$			50		$\Omega$
RF2 Port Impedance	$Z_{RF2}$			50		
Operating Temperature Range	$T_{CASE}$	Exposed Paddle Temperature	-40		+105	°C

### Operating Conditions Notes:

- 1 – Items in min/max columns in ***bold italics*** are Guaranteed by Test.
- 2 – Items in min/max columns that are not bold/italics are Guaranteed by Design Characterization.
- 3 – Refer to the Maximum **Operating** RF Input Power vs. RF Frequency curves in Figure 1.

## IDTF2255 SPECIFICATIONS

Refer to EVKit / Applications Circuit,  $V_{DD} = +3.3V$ ,  $T_c = +25^\circ C$ , signals applied to RF1 input,  $F_{RF} = 500MHz$ , minimum attenuation,  $P_{IN} = 0dBm$  for small signal parameters,  $+20dBm$  for single tone linearity tests,  $+20dBm$  per tone for two tone tests, two tone delta frequency =  $80MHz$ , PCB board traces and connector losses are de-embedded unless otherwise noted. Refer to Typical Operating Curves for performance over entire frequency band.

Parameter	Symbol	Condition	Min	Typ	Max	Units
Insertion Loss, IL	A <sub>MIN</sub>	Minimum Attenuation		1.1	<b>1.7<sup>1</sup></b>	dB
Maximum attenuation	A <sub>MAX</sub>		33	34.6		dB
Insertion Phase $\Delta$	$\Phi_{\Delta MAX}$	At 36dB attenuation relative to Insertion Loss		27		deg
	$\Phi_{\Delta MID}$	At 18dB attenuation relative to Insertion Loss		8		
Input 1dB Compression <sup>3</sup>	P <sub>1dB</sub>			36		dBm
Minimum RF1 Return Loss over control voltage range	S <sub>11</sub>	20MHz		23		dB
		500MHz		22		
		2000MHz		23		
		3000MHz		30		
Minimum RF2 Return Loss over control voltage range	S <sub>22</sub>	20MHz		23		dB
		500MHz		22		
		2000MHz		23		
		3000MHz		24		
Input IP3	IIP3			60		dBm
Input IP3 over Attenuation	IIP3 <sub>ATTEN</sub>	All attenuation settings	44 <sup>2</sup>	46		
Minimum Output IP3	OIP3 <sub>MIN</sub>	Maximum attenuation		35		
Input IP2	IIP2	PIN + IM2 <sub>dBC</sub> , IM2 term is F1+F2		98		dBm
Minimum Input IP2	IIP2 <sub>MIN</sub>	All attenuation settings		74		dBm
Input IH2	HD2	PIN + H2 <sub>dBC</sub>		82		dBm
Input IH3	HD3	PIN + (H3 <sub>dBC</sub> /2)		49		dBm
Settling Time	T <sub>SETTLE0.1dB</sub>	Any 1dB step in the 0dB to 33dB control range 50% V <sub>CTRL</sub> to RF settled to within $\pm 0.1dB$		15		µSec

### Specification Notes:

- 1 – Items in min/max columns in ***bold italics*** are Guaranteed by Test.
- 2 – Items in min/max columns that are not bold/italics are Guaranteed by Design Characterization.
- 3 – The input 1dB compression point is a linearity figure of merit. Refer to Absolute Maximum Ratings section along with Figure 1 for the maximum RF input power vs. RF frequency.

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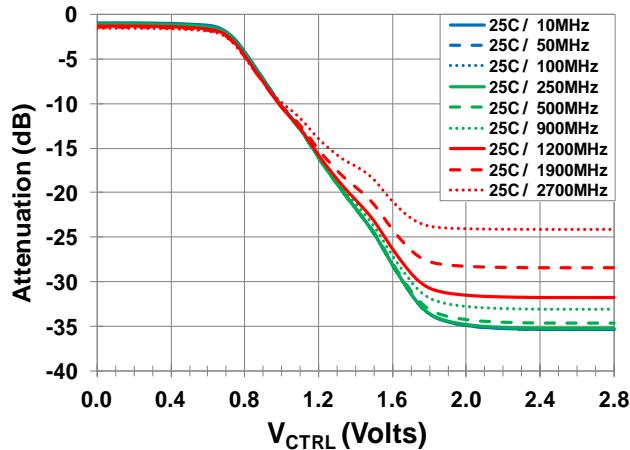
## TYPICAL OPERATING CURVES

### UNLESS OTHERWISE NOTED, THE FOLLOWING CONDITIONS APPLY:

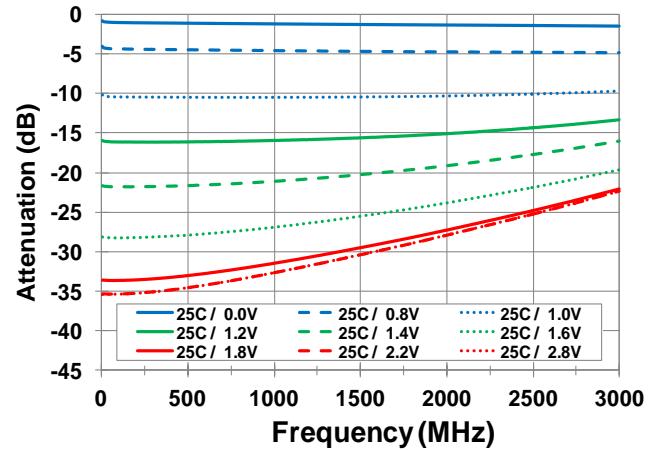
- $V_{DD} = +3.3V$  or  $+5.0V$
- $T_C = +25^\circ C$
- $V_{MODE} = 0V$
- RF trace and connector losses are de-embedded for S-parameters
- Pin = 0dBm for all small signal tests
- Pin = +20dBm for single tone linearity tests (RF1 port driven)
- Pin = +20dBm/tone for two tone linearity tests (RF1 port driven)
- Two tone frequency spacing = 80MHz

## TYPICAL OPERATING CONDITIONS [S2P BROADBAND PERFORMANCE] (-1-)

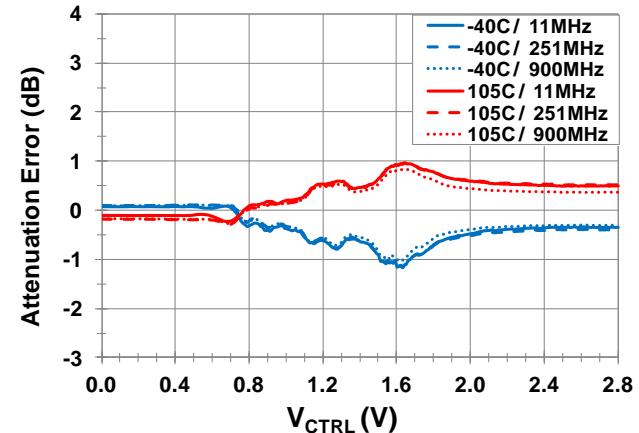
**Attenuation vs.  $V_{CTRL}$**



**Attenuation vs. Frequency**

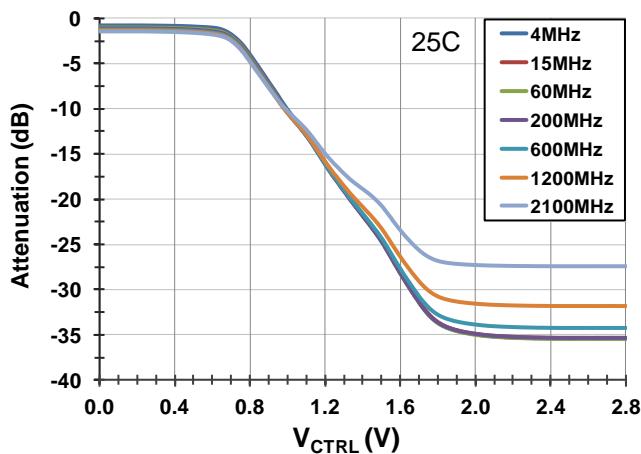


**Attenuation Delta to 25C vs.  $V_{CTRL}$**

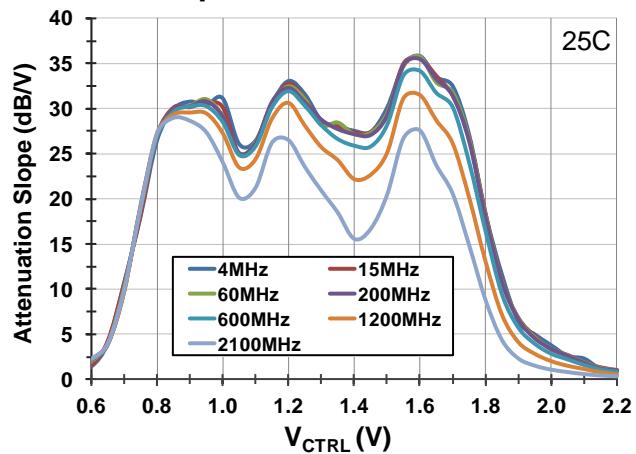


## TYPICAL OPERATING CURVES [S2P vs. $V_{CTRL}$ ] (-2-)

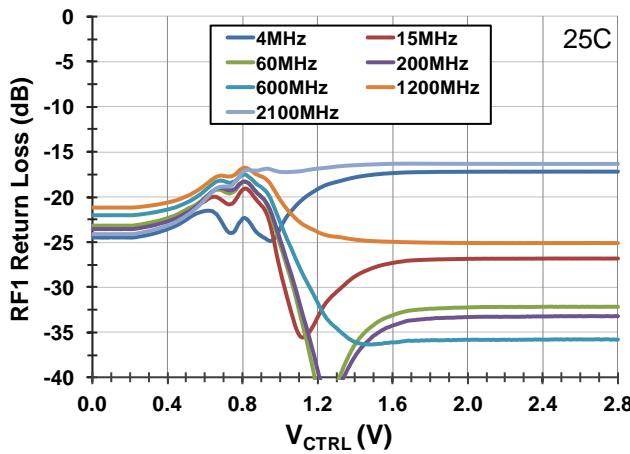
**Attenuation vs.  $V_{CTRL}$**



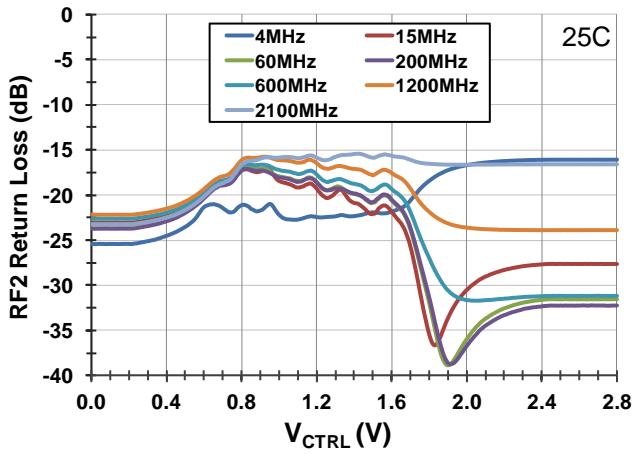
**Attenuation Slope vs.  $V_{CTRL}$**



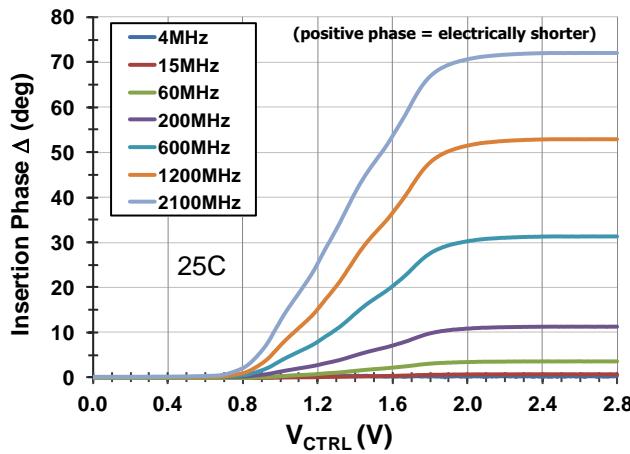
**RF1 Return Loss vs.  $V_{CTRL}$**



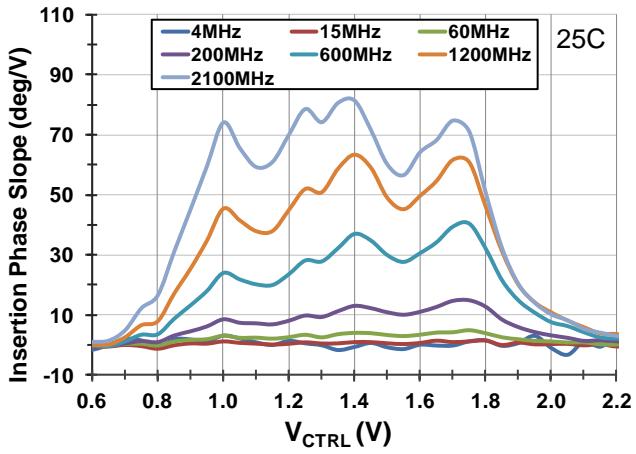
**RF2 Return Loss vs.  $V_{CTRL}$**



**Insertion Phase  $\Delta$  vs.  $V_{CTRL}$**

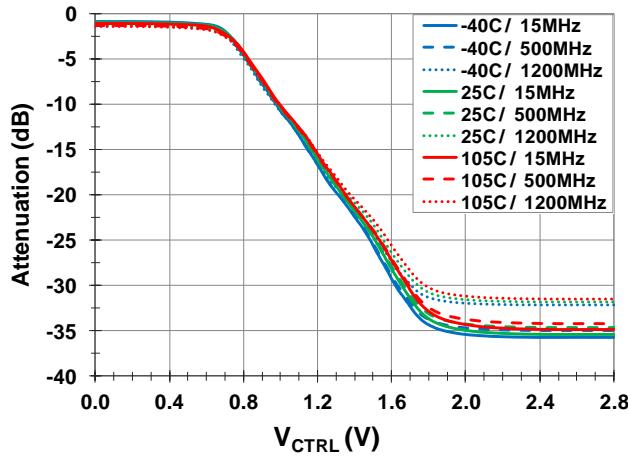


**Insertion Phase Slope vs.  $V_{CTRL}$**

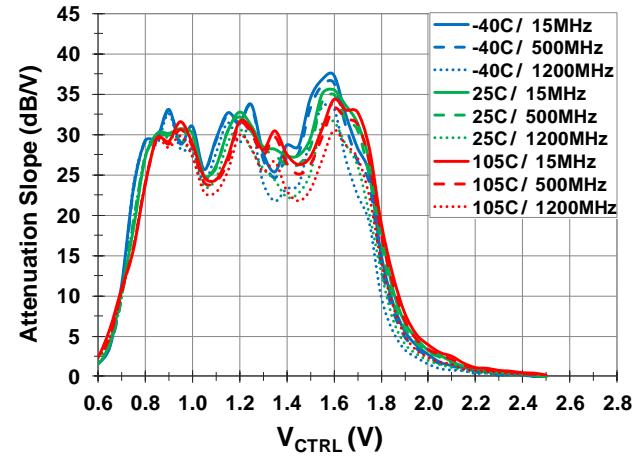


### TYPICAL OPERATING CONDITIONS [S2P VS. $V_{CTRL}$ & TEMPERATURE] (-3-)

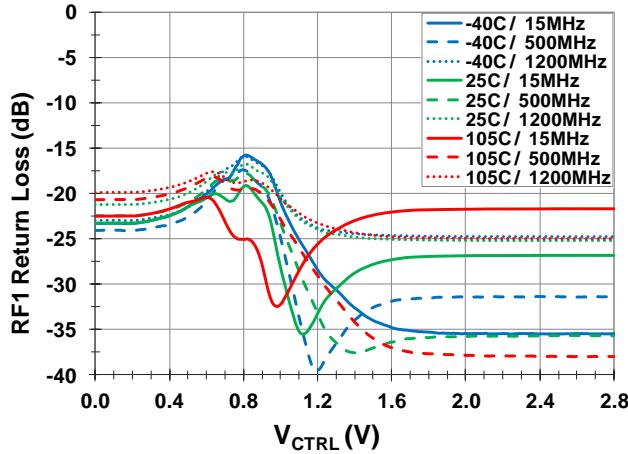
**Attenuation Response vs.  $V_{CTRL}$**



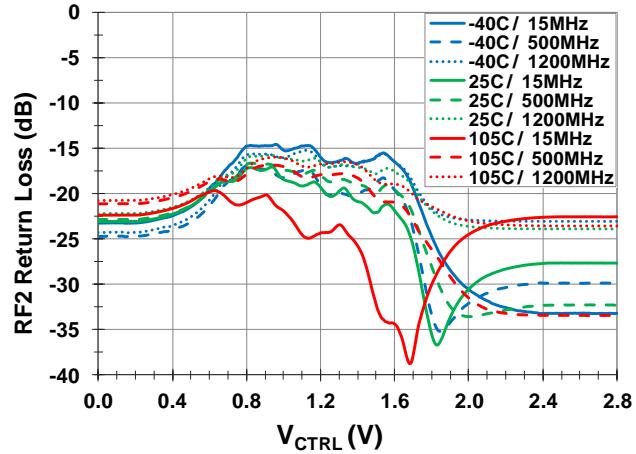
**Attenuation Slope vs.  $V_{CTRL}$**



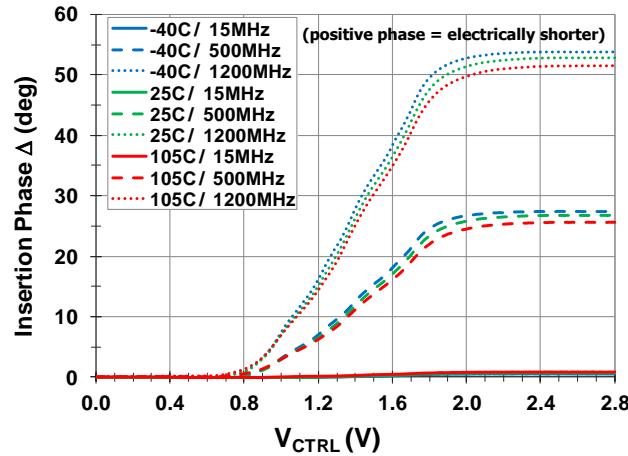
**RF1 Return Loss vs.  $V_{CTRL}$**



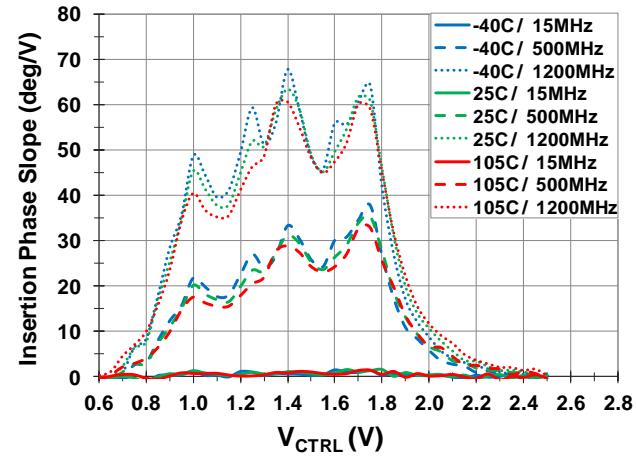
**RF2 Return Loss vs.  $V_{CTRL}$**



**Insertion Phase  $\Delta$  vs.  $V_{CTRL}$**

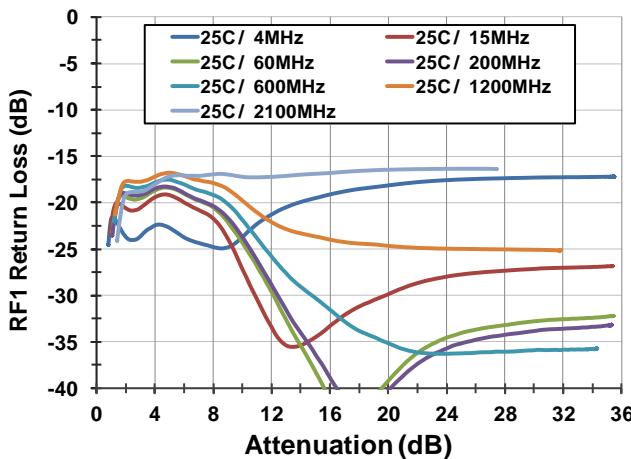


**Insertion Phase Slope vs.  $V_{CTRL}$**

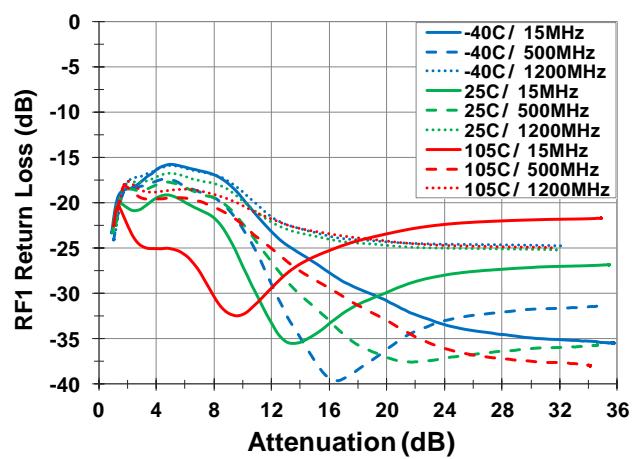


## TYPICAL OPERATING CONDITIONS [S2P VS. ATTENUATION & TEMPERATURE] (-4-)

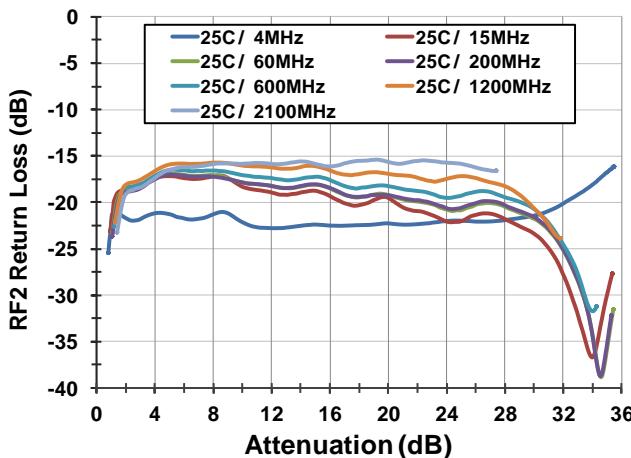
**RF1 Return Loss vs. Attenuation**



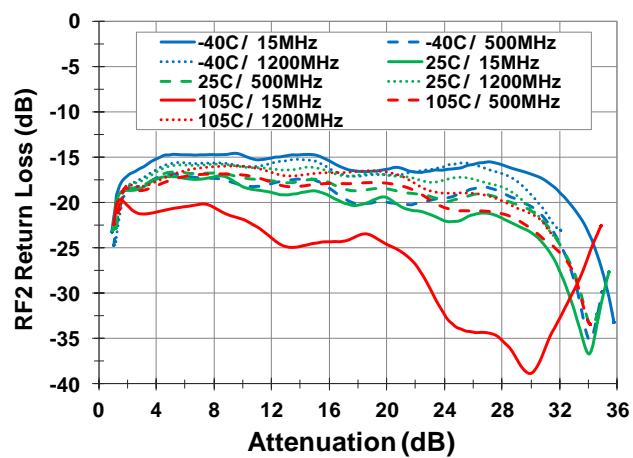
**RF1 Return Loss vs. Attenuation**



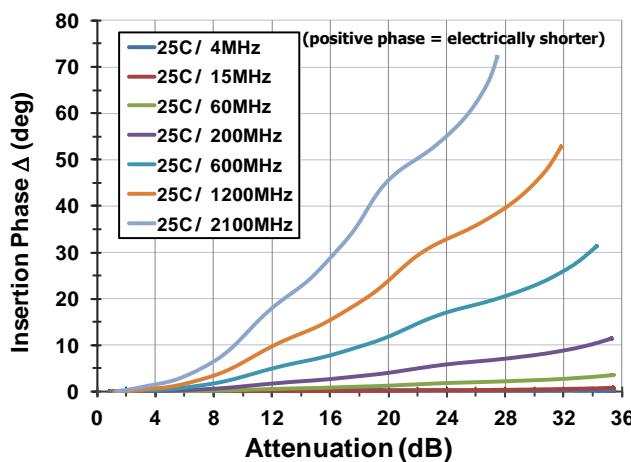
**RF2 Return Loss vs. Attenuation**



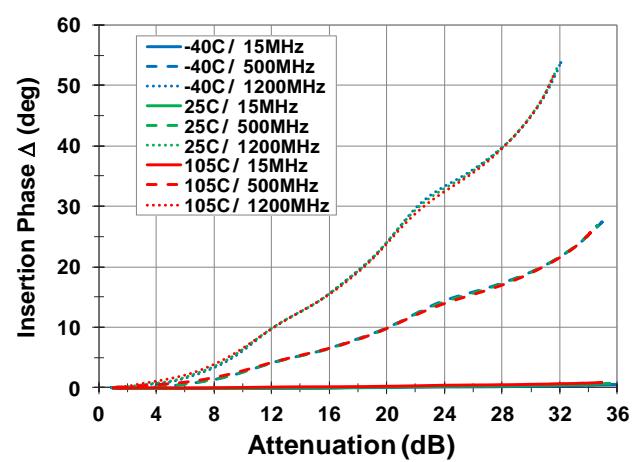
**RF2 Return Loss vs. Attenuation**



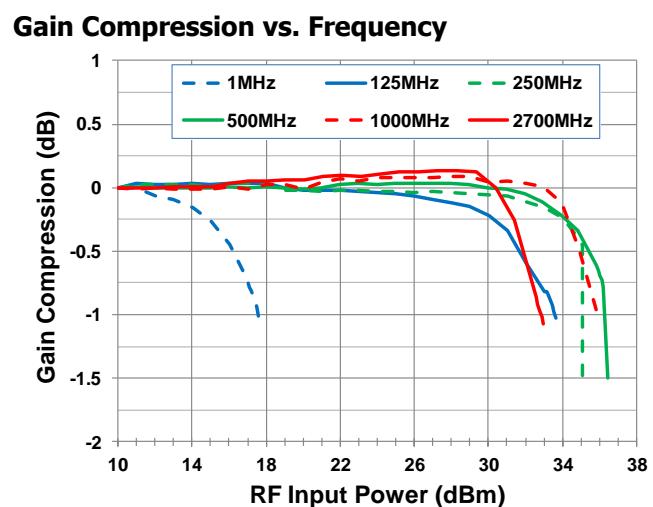
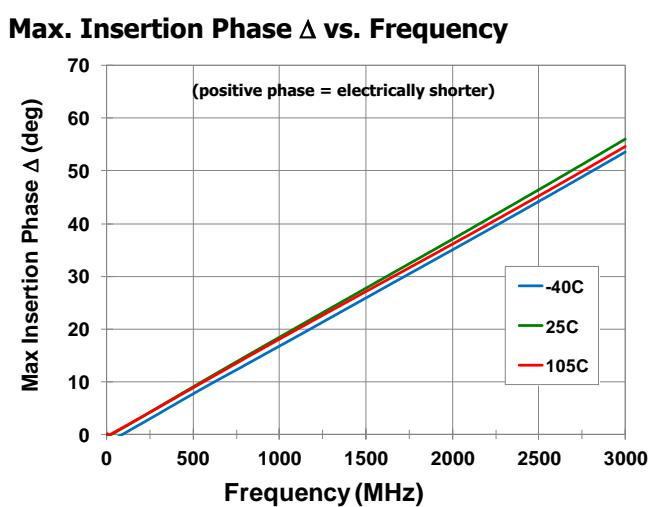
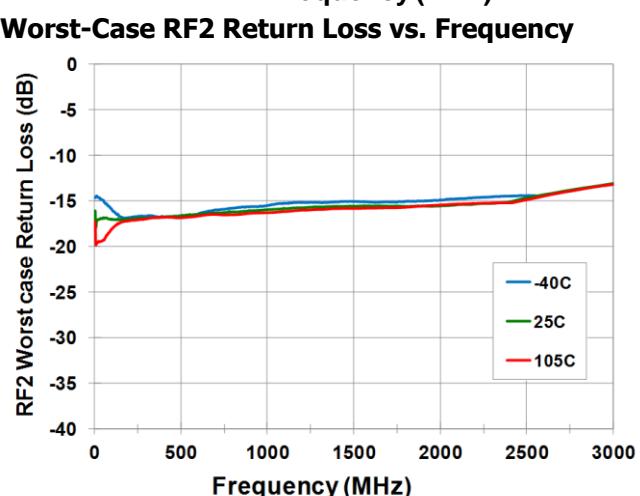
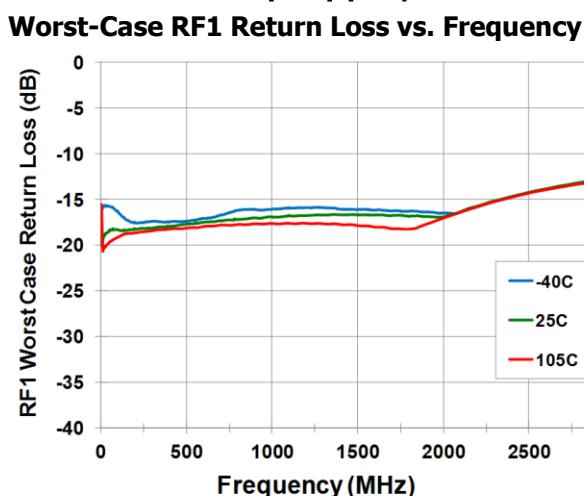
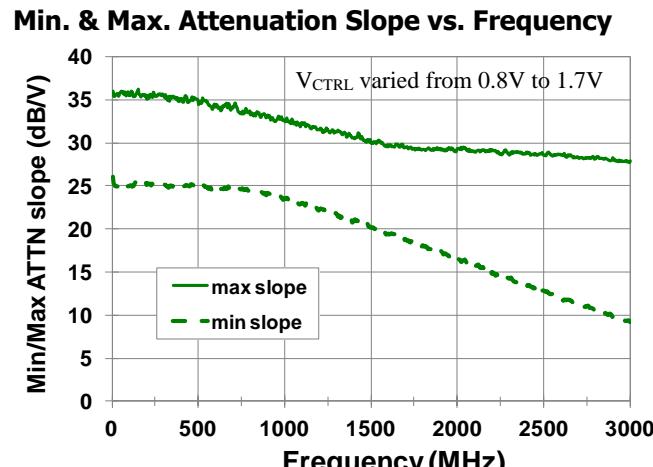
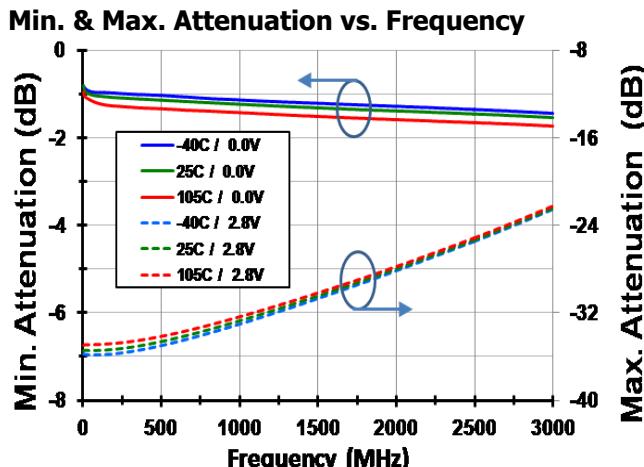
**Insertion Phase  $\Delta$  vs. Attenuation**



**Insertion Phase  $\Delta$  vs. Attenuation**

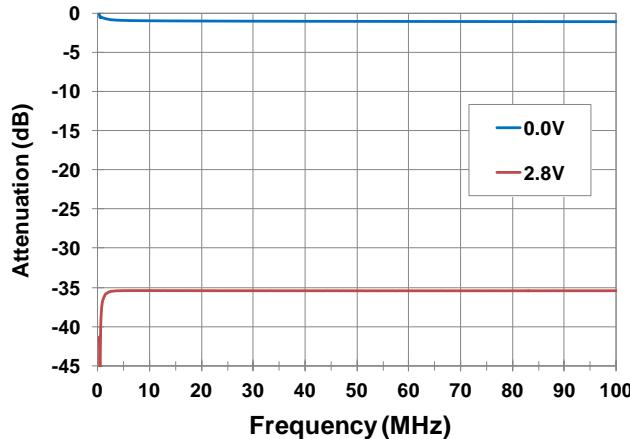


### TYPICAL OPERATING CONDITIONS [S2P vs. FREQUENCY] (-5-)

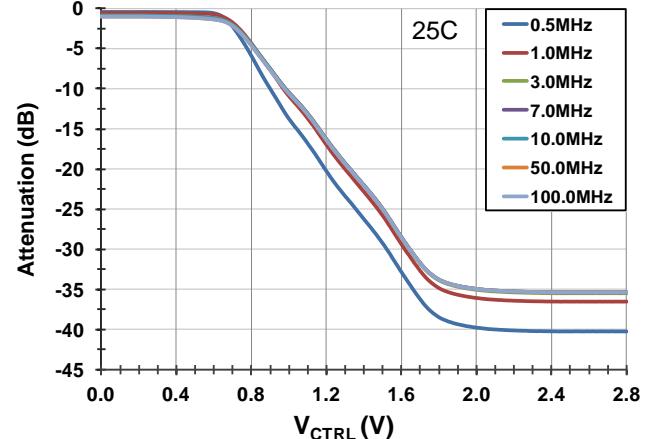


### TYPICAL OPERATING CONDITIONS [S2P @ LOW FREQUENCY, GROUP DELAY] (-6-)

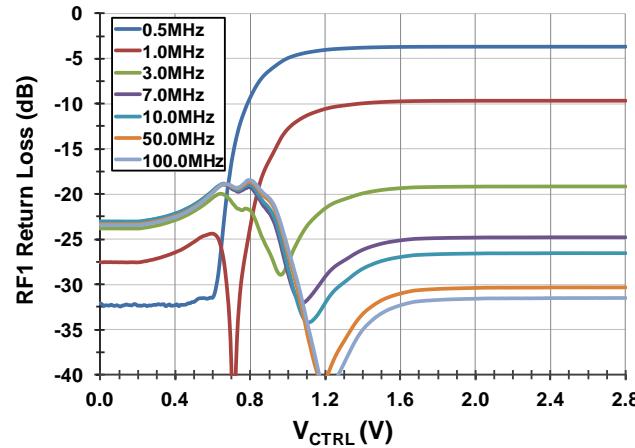
**Min. & Max. Attenuation vs. Low Frequency**



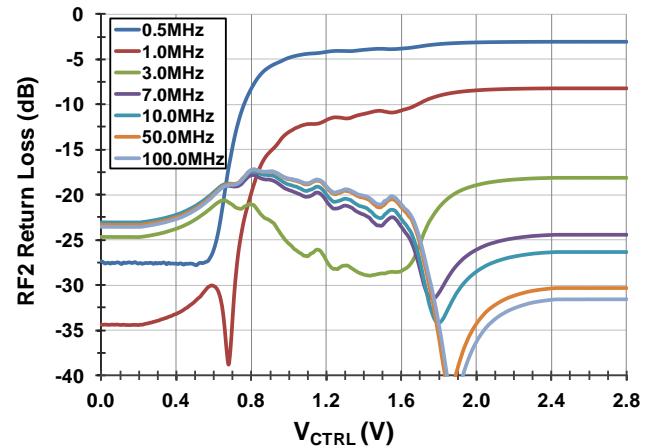
**Low-Frequency Attenuation vs.  $V_{CTRL}$**



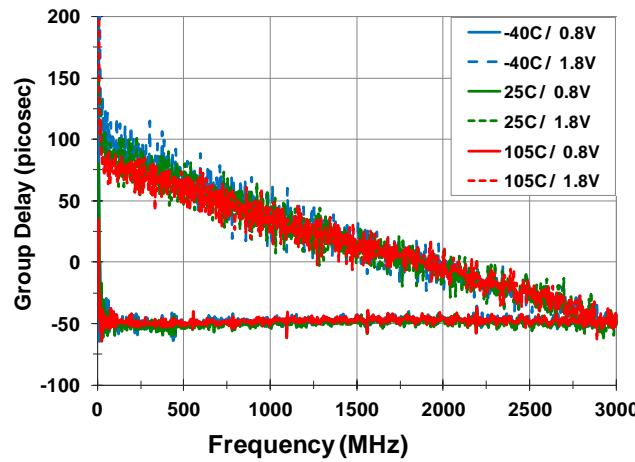
**Low-Frequency RF1 Return Loss vs.  $V_{CTRL}$**

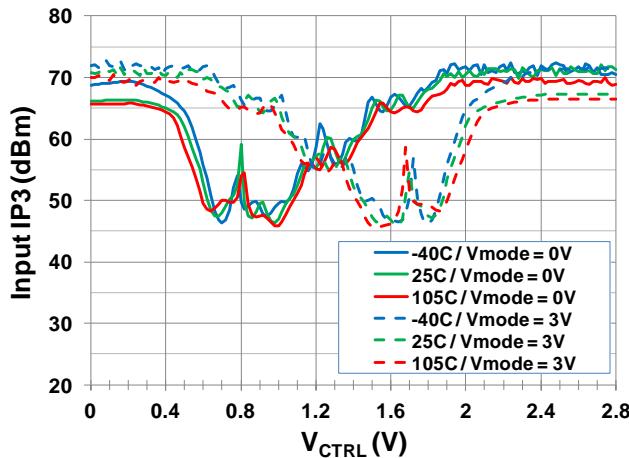
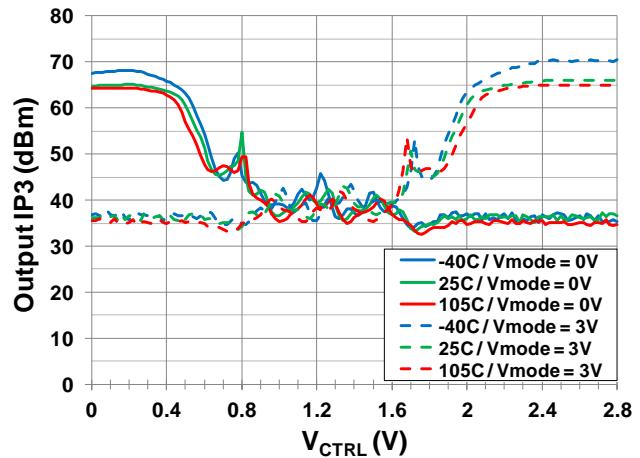
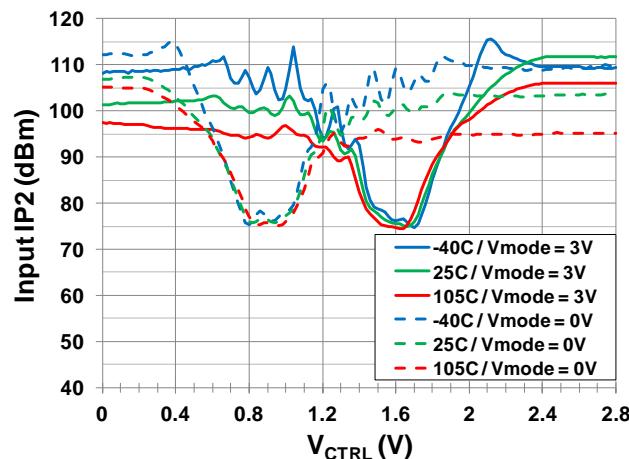
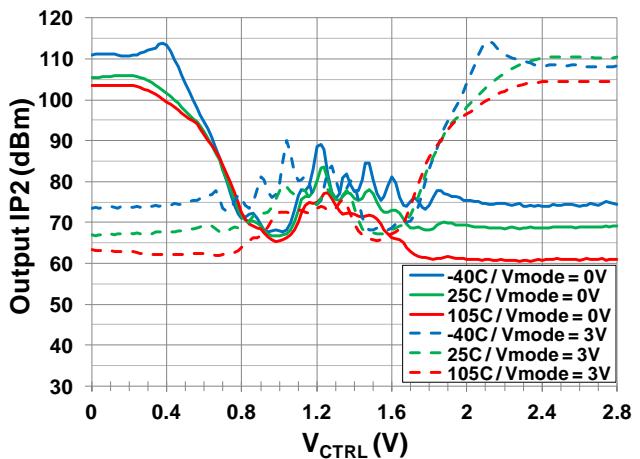
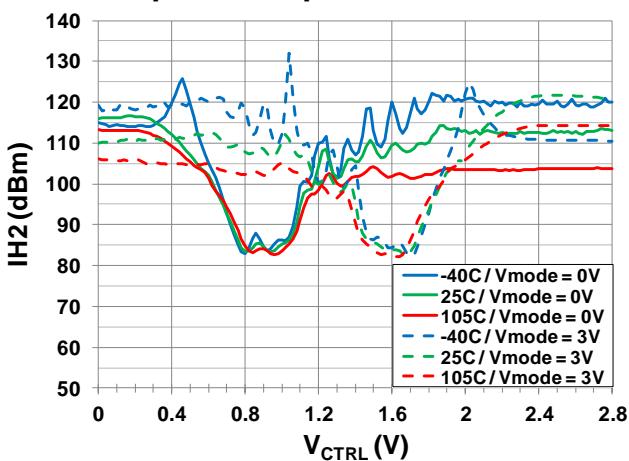
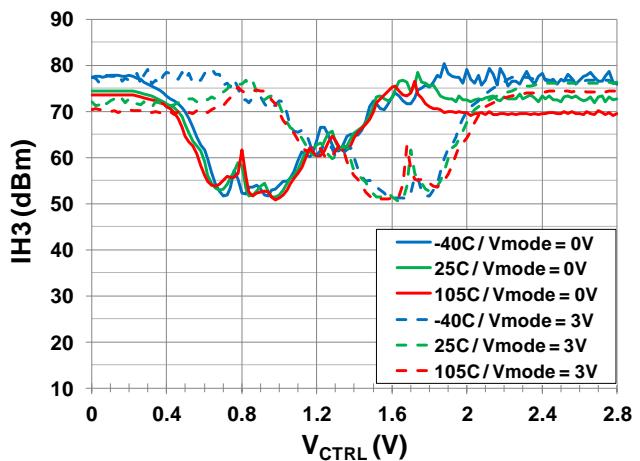


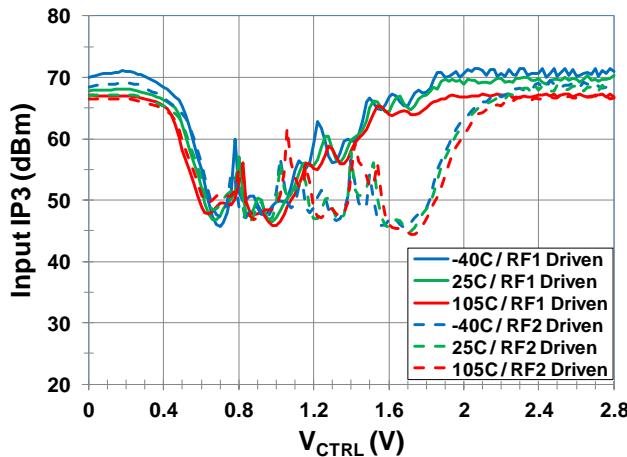
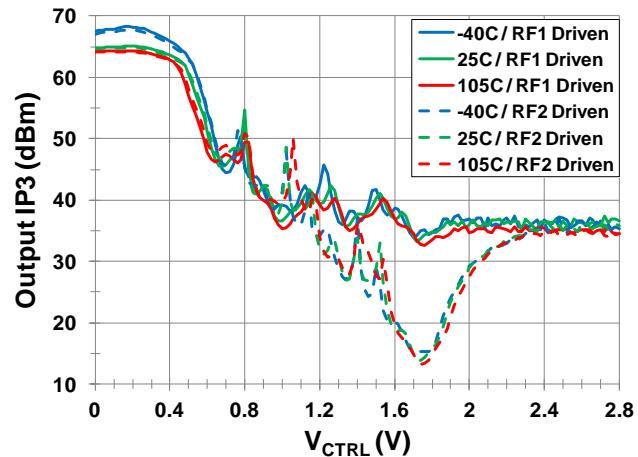
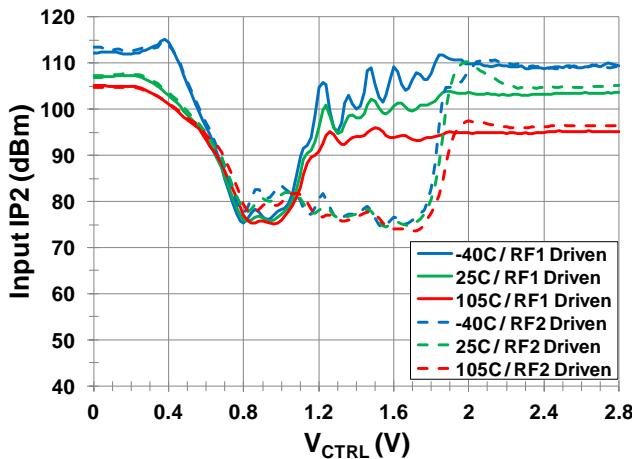
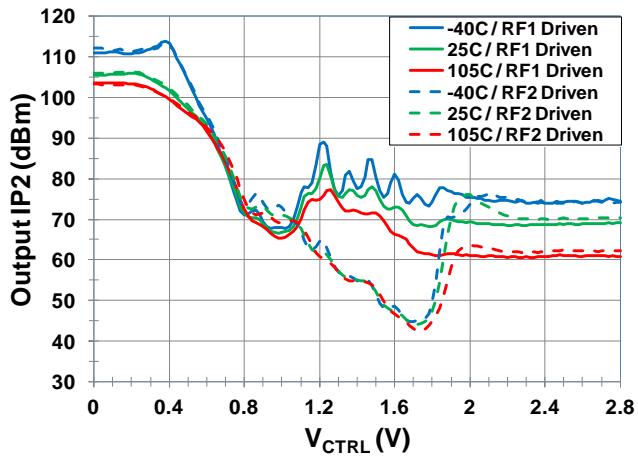
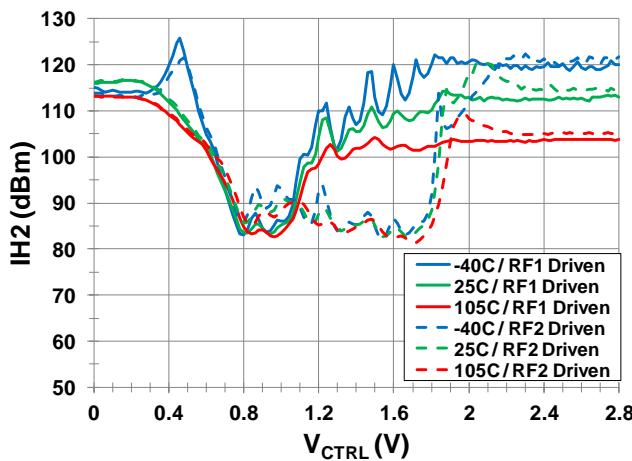
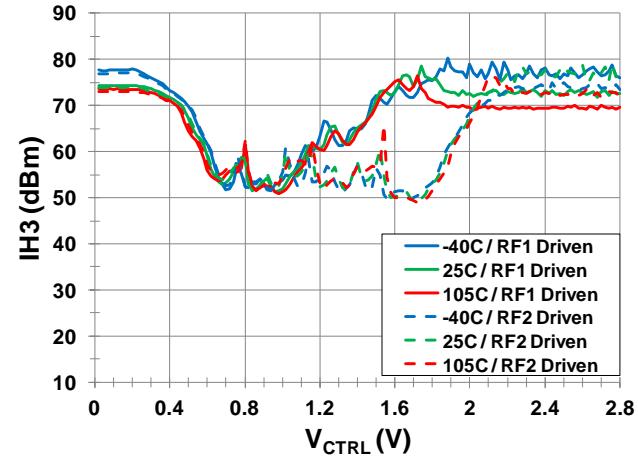
**Low-Frequency RF2 Return Loss vs.  $V_{CTRL}$**

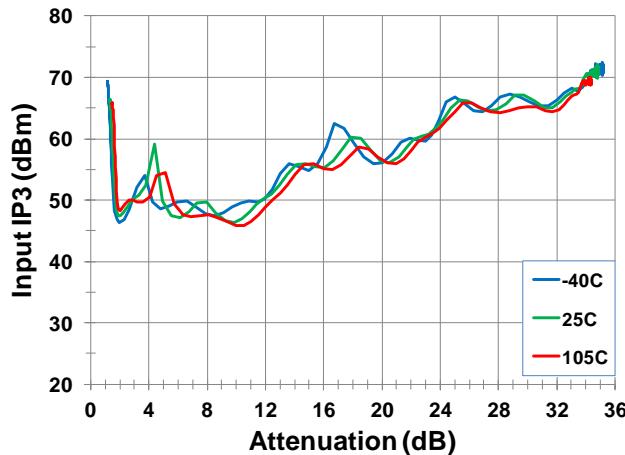
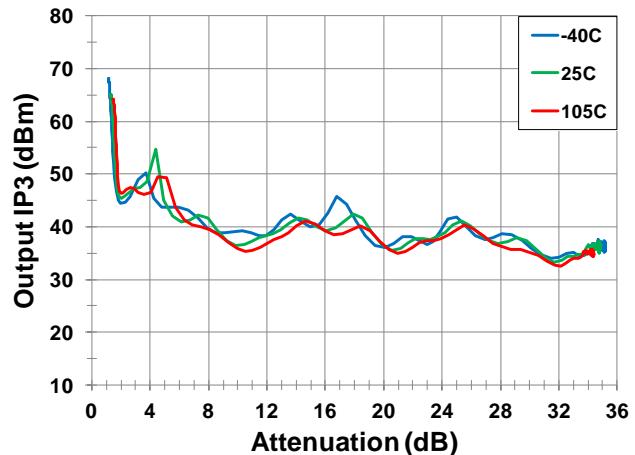
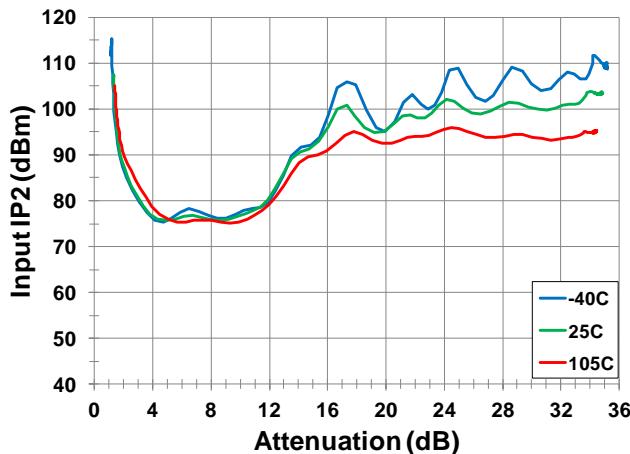
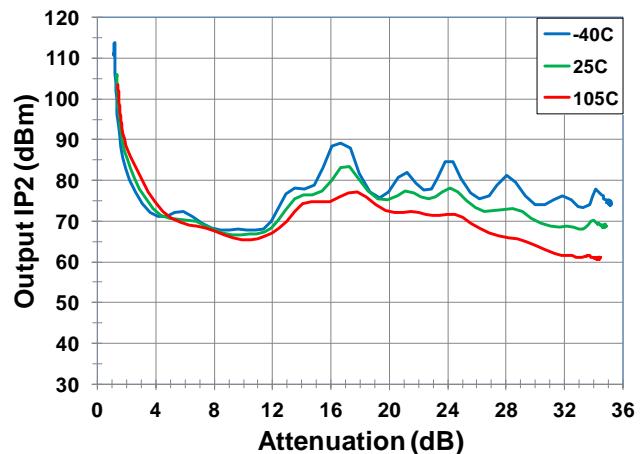
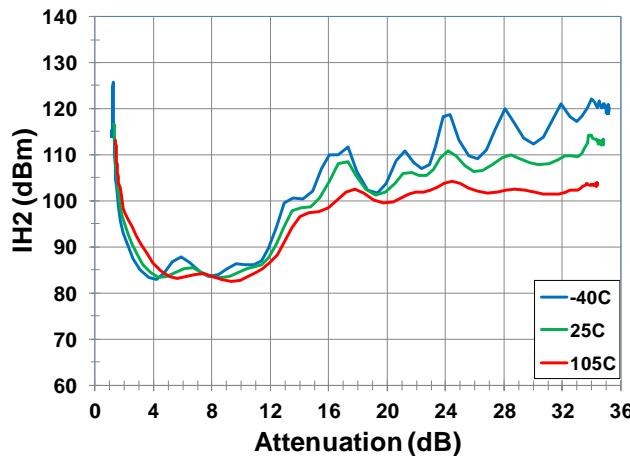
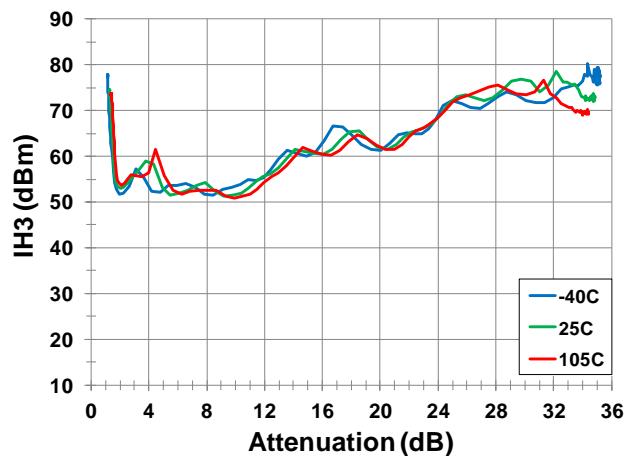


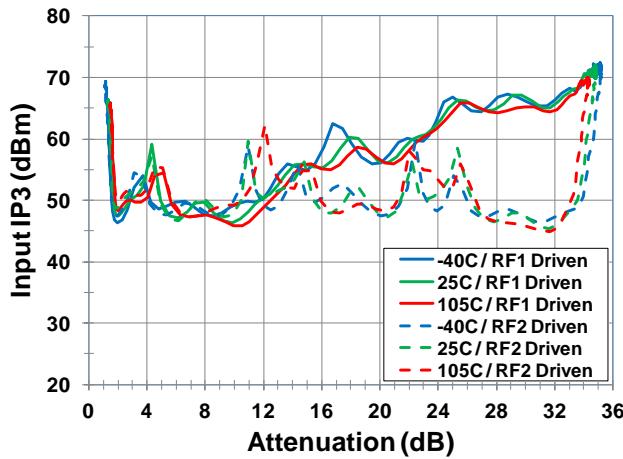
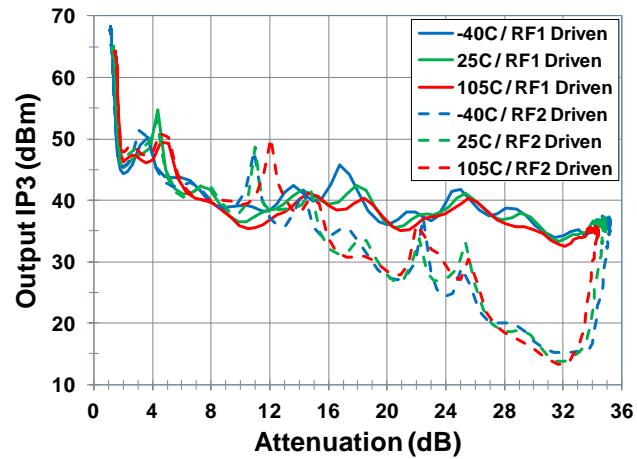
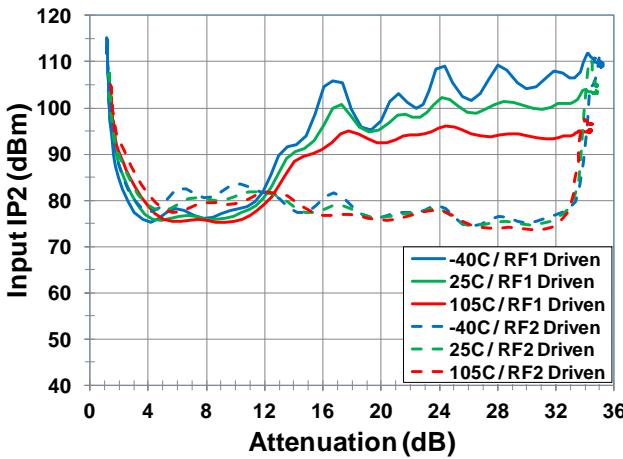
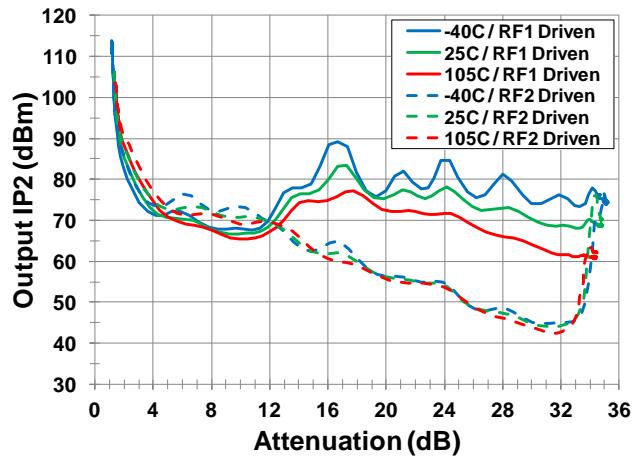
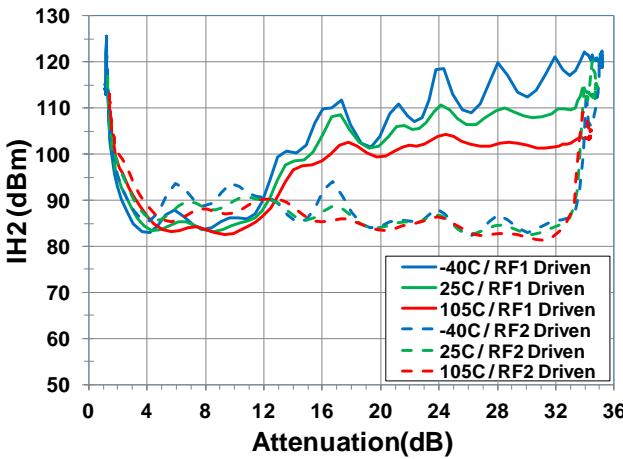
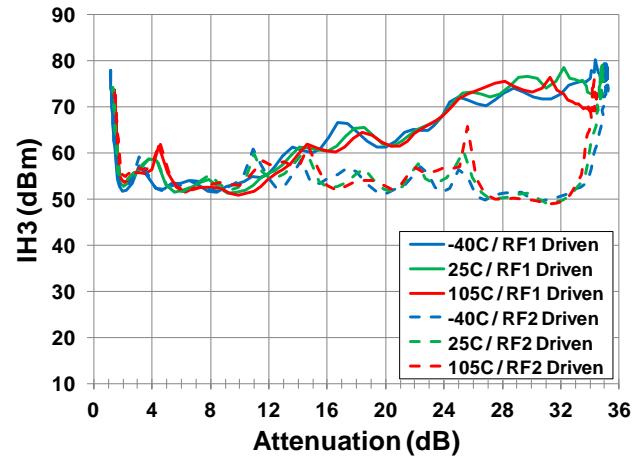
**Group Delay vs. Frequency**



**TYPICAL OPERATING CONDITIONS 500MHZ, V<sub>DD</sub>=3.3V [IP3, IP2, IH2, IH3 VS. V<sub>CTRL</sub>, V<sub>MODE</sub>] (-7-)**
**Input IP3 vs. V<sub>CTRL</sub>**

**Output IP3 vs. V<sub>CTRL</sub>**

**Input IP2 vs. V<sub>CTRL</sub>**

**Output IP2 vs. V<sub>CTRL</sub>**

**2<sup>nd</sup> Harm Input Intercept Point vs. V<sub>CTRL</sub>**

**3<sup>rd</sup> Harm Input Intercept Point vs. V<sub>CTRL</sub>**


**TYPICAL OPERATING CONDITIONS 500MHZ, V<sub>DD</sub>=3.3V [IP<sub>X</sub>, IH<sub>X</sub> VS. V<sub>CTRL</sub>, RF1/RF2 DRIVEN] (-8-)**
**Input IP3 vs. V<sub>CTRL</sub>**

**Output IP3 vs. V<sub>CTRL</sub>**

**Input IP2 vs. V<sub>CTRL</sub>**

**Output IP2 vs. V<sub>CTRL</sub>**

**2<sup>nd</sup> Harm Input Intercept Point vs. V<sub>CTRL</sub>**

**3<sup>rd</sup> Harm Input Intercept Point vs. V<sub>CTRL</sub>**


**TYPICAL OPERATING CONDITIONS 500MHZ, V<sub>DD</sub>=3.3V [IP3, IP2, IH2, IH3 vs. ATTENUATION] (-9-)**
**Input IP3 vs. Attenuation**

**Output IP3 vs. Attenuation**

**Input IP2 vs. Attenuation**

**Output IP2 vs. Attenuation**

**2<sup>nd</sup> Harm Input Intercept Point vs. Attenuation**

**3<sup>rd</sup> Harm Input Intercept Point vs. Attenuation**


**TYPICAL OPERATING CONDITIONS 500MHZ, V<sub>DD</sub>=3.3V [IP<sub>X</sub>, IH<sub>X</sub> vs. ATTEN, RF1/RF2 DRIVEN] (-10-)**
**Input IP3 vs. Attenuation**

**Output IP3 vs. Attenuation**

**Input IP2 vs. Attenuation**

**Output IP2 vs. Attenuation**

**2<sup>nd</sup> Harm Input Intercept Point vs. Attenuation**

**3<sup>rd</sup> Harm Input Intercept Point vs. Attenuation**


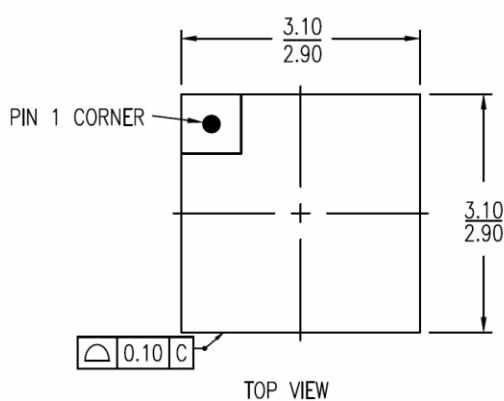
**PACKAGE DRAWING (3MM X 3MM 16 PIN)**



**16-VFQFPN Package Outline Drawing**

3.0 x 3.0 x 0.9 mm, 0.5mm Pitch, 1.70 x 1.70 mm Epad

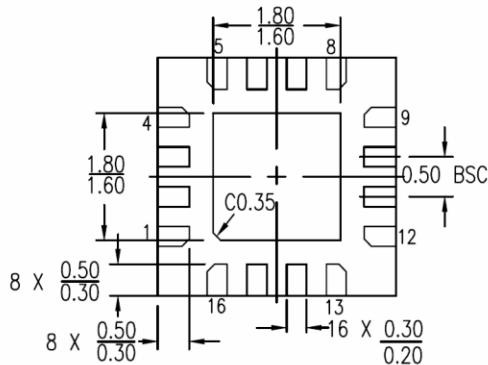
NL/NLG16P2, PSC-4169-02, Rev 05, Page 1



TOP VIEW



SIDE VIEW

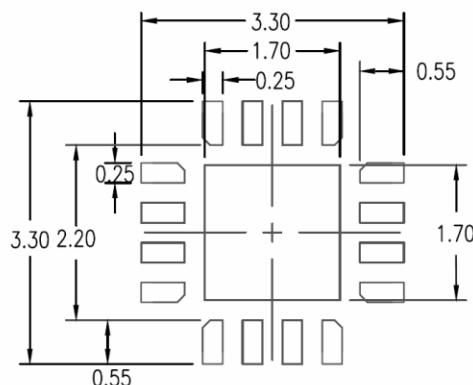


BOTTOM VIEW

NOTES:

1. ALL DIMENSIONS ARE IN mm. ANGLES IN DEGREES

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**LAND PATTERN DRAWING****16-VFQFPN Package Outline Drawing**3.0 x 3.0 x 0.9 mm, 0.5mm Pitch, 1.70 x 1.70 mm Epad  
NL/NLG16P2, PSC-4169-02, Rev 05, Page 2

RECOMMENDED LAND PATTERN DIMENSION

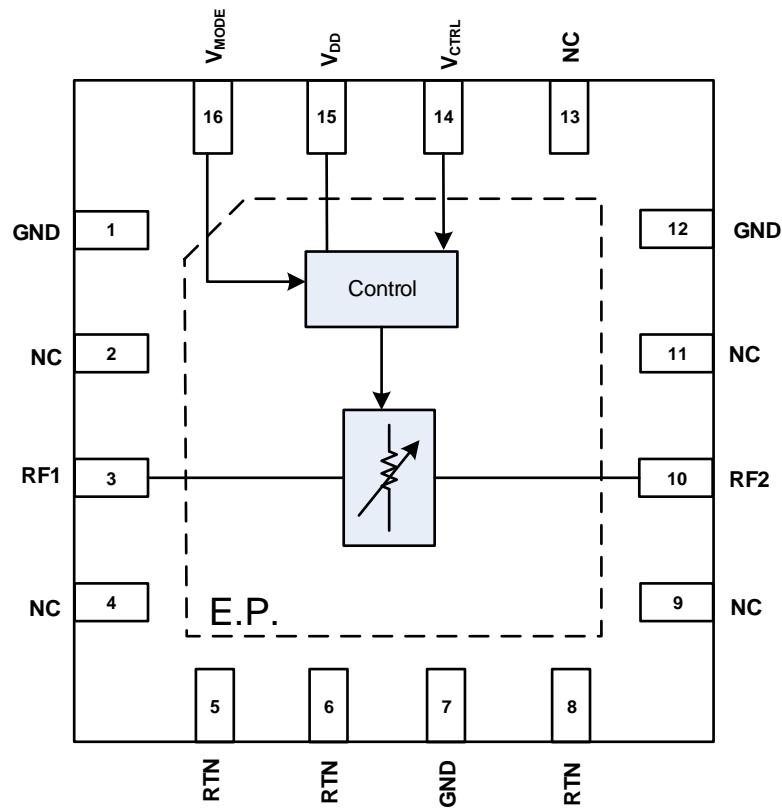
## NOTES:

1. ALL DIMENSIONS ARE IN mm. ANGLES IN DEGREES
2. TOP DOWN VIEW—AS VIEWED ON PCB
3. LAND PATTERN RECOMMENDATION IS PER IPC-7351B GENERIC REQUIREMENT FOR SURFACE MOUNT DESIGN AND LAND PATTERN

Package Revision History		
Date Created	Rev No.	Description
Oct 25, 2017	Rev 04	Remove Bookmak at Pdf Format & Update Thickness Tolerance
Jan 18, 2018	Rev 05	Change QFN to VFQFPN

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## PINOUT & BLOCK DIAGRAM



## PIN DESCRIPTION

<b>Pin</b>	<b>Name</b>	<b>Function</b>
1, 7, 12	GND	Ground these pins as close to the device as possible.
2, 4, 9, 11, 13	NC	No internal connection. IDT recommends connecting these pins to GND.
3	RF1	RF Port 1. Matched to 50 ohms. Must use an external AC coupling capacitor as close to the device as possible. For low frequency operation increase the capacitor value to result in a low reactance at the frequency of interest.
5, 6, 8	RTN	Attenuator Ground Return. Each of these pins require a capacitor to GND to provide an RF return path. Place the capacitor as close to the device as possible.
10	RF2	RF Port 2. Matched to 50 ohms. Must use an external AC coupling capacitor as close to the device as possible. For low frequency operation increase the capacitor value to result in a low reactance at the frequency of interest.
14	V <sub>CTRL</sub>	Attenuator control voltage. Apply a voltage in the range as specified in the Operating Conditions Table. See application section for details about V <sub>CTRL</sub> .
15	V <sub>DD</sub>	Power supply input. Bypass to GND with capacitors close as possible to pin.
16	V <sub>MODE</sub>	Attenuator slope control. Set to logic LOW to enable negative attenuation slope. Set to logic HIGH to enable positive attenuation slope.
	— EP	Exposed Pad. Internally connected to GND. Solder this exposed pad to a PCB pad that uses multiple ground vias to achieve the specified RF performance.

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## APPLICATIONS INFORMATION

### Default Start-up

$V_{MODE}$  must be tied to either GND or Logic High. If the  $V_{CTRL}$  pin is left floating, the part will power up in the minimum attenuation state when  $V_{MODE} = \text{GND}$ , or the maximum attenuation state when  $V_{MODE} = \text{High}$ .

#### $V_{CTRL}$

The voltage level on the  $V_{CTRL}$  pin is used to control the attenuation of the F2255. At  $V_{CTRL} = 0\text{V}$ , the attenuation is a minimum (maximum) in the negative (positive) slope mode. An increasing (decreasing) voltage on  $V_{CTRL}$  produces an increasing (decreasing) attenuation respectively. The  $V_{CTRL}$  pin has an on-chip pull-up ESD diode so  $V_{DD}$  should be applied before  $V_{CTRL}$  is applied (see Recommended Operating Conditions for details). If this sequencing is not possible, then resistor R2 in the application circuit should be set to  $1\text{k}\Omega$  to limit the current into the  $V_{CTRL}$  pin.

#### $V_{MODE}$

The  $V_{MODE}$  pin is used to set the slope of the attenuation. The attenuation is varied by  $V_{CTRL}$  as described in the next section. Setting  $V_{MODE}$  to a logic LOW (HIGH) will set the attenuation slope to negative (positive). A negative (positive) slope is defined as an increased (decreased) attenuation with increasing  $V_{CTRL}$  voltage. The Evaluation Kit provides an on-board jumper to manually set the  $V_{MODE}$ . Install a jumper on header J2 from  $V_{MODE}$  to the pin marked Lo (Hi) to set the device for a negative (positive) slope (see application circuit).

### RF1 and RF2 Ports

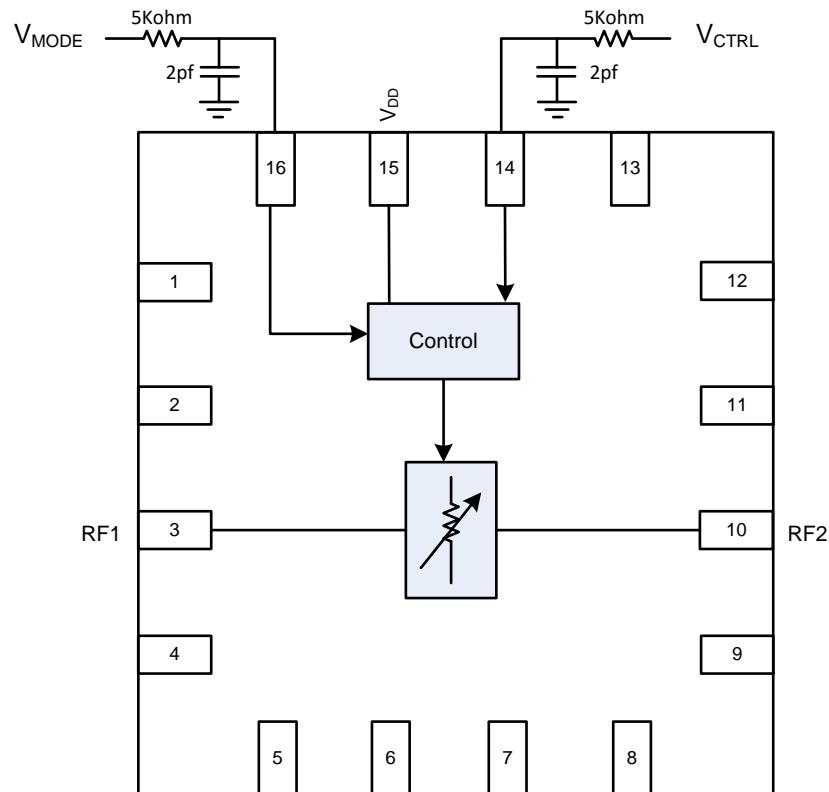
The F2255 is a bi-directional device, allowing RF1 or RF2 to be used as the RF input. RF1 has some enhanced linearity performance, and therefore should be used as the RF input, when possible, for best results. The F2255 has been designed to accept high RF input power levels; therefore,  $V_{DD}$  must be applied prior to the application of RF power to ensure reliability. DC blocking capacitors are required on the RF pins and should be set to a value that results in a low reactance over the frequency range of interest.

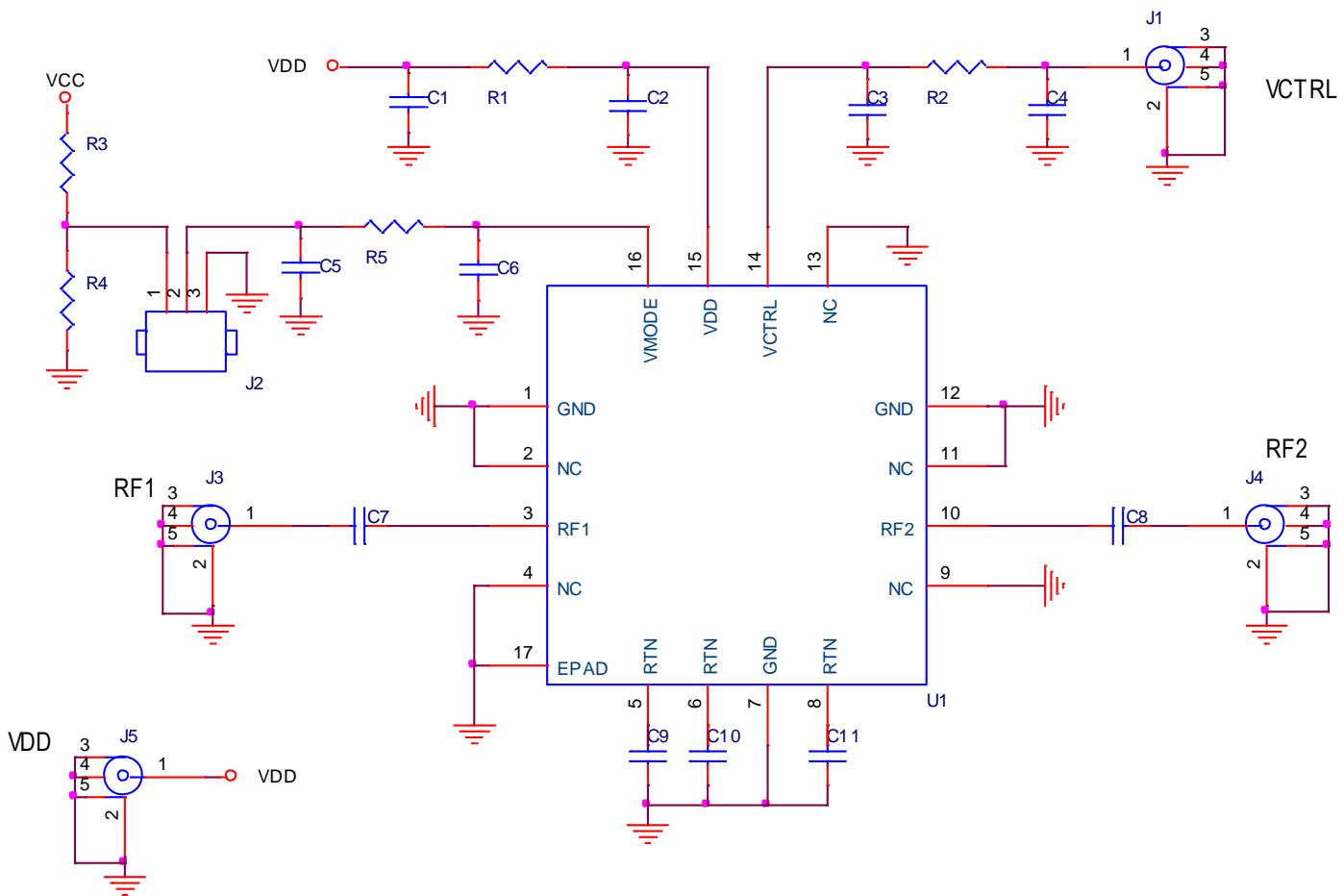
### Power Supplies

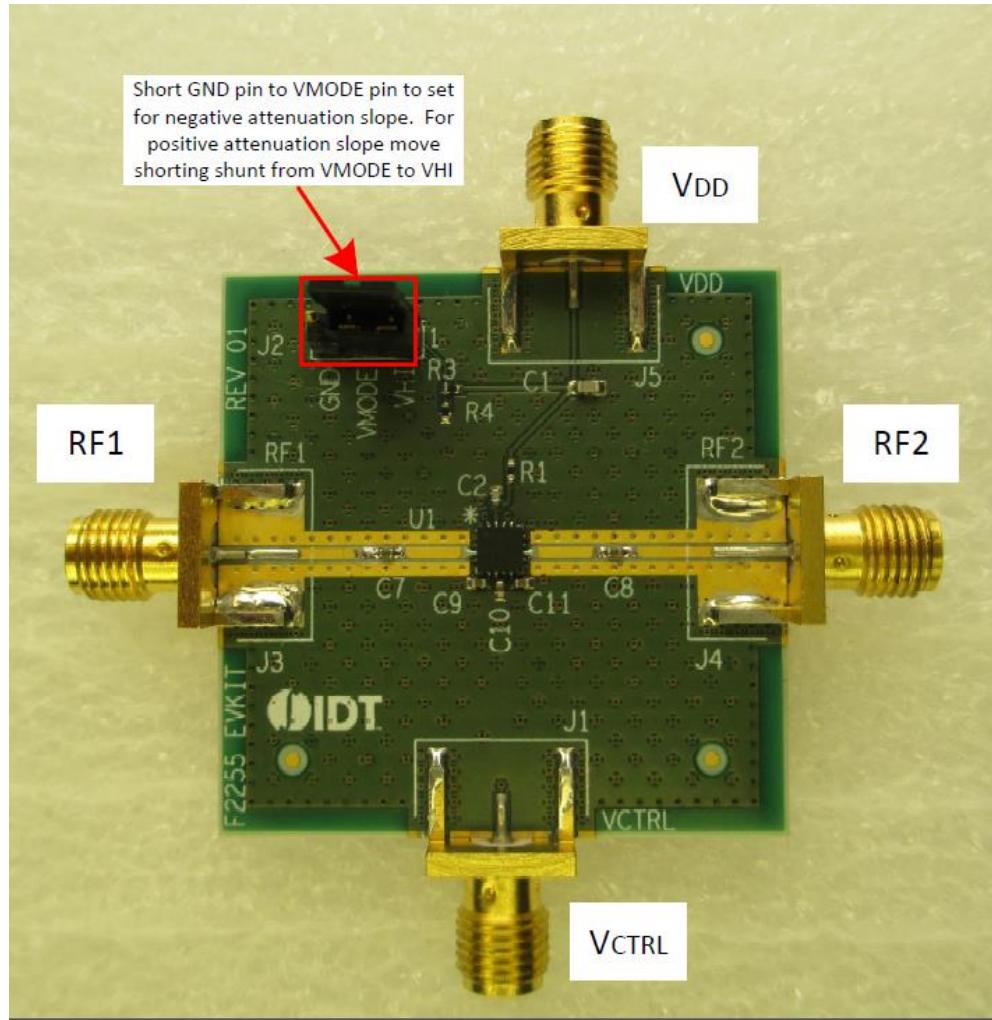
The supply pin should be bypassed with external capacitors to minimize noise and fast transients. Supply noise can degrade noise figure and fast transients can trigger ESD clamps and cause them to fail. Supply voltage change or transients should have a slew rate smaller than  $1\text{V}/20\mu\text{s}$ . In addition, all control pins should remain at  $0\text{V}$  ( $+/-0.3\text{V}$ ) while the supply voltage ramps or while it returns to zero.

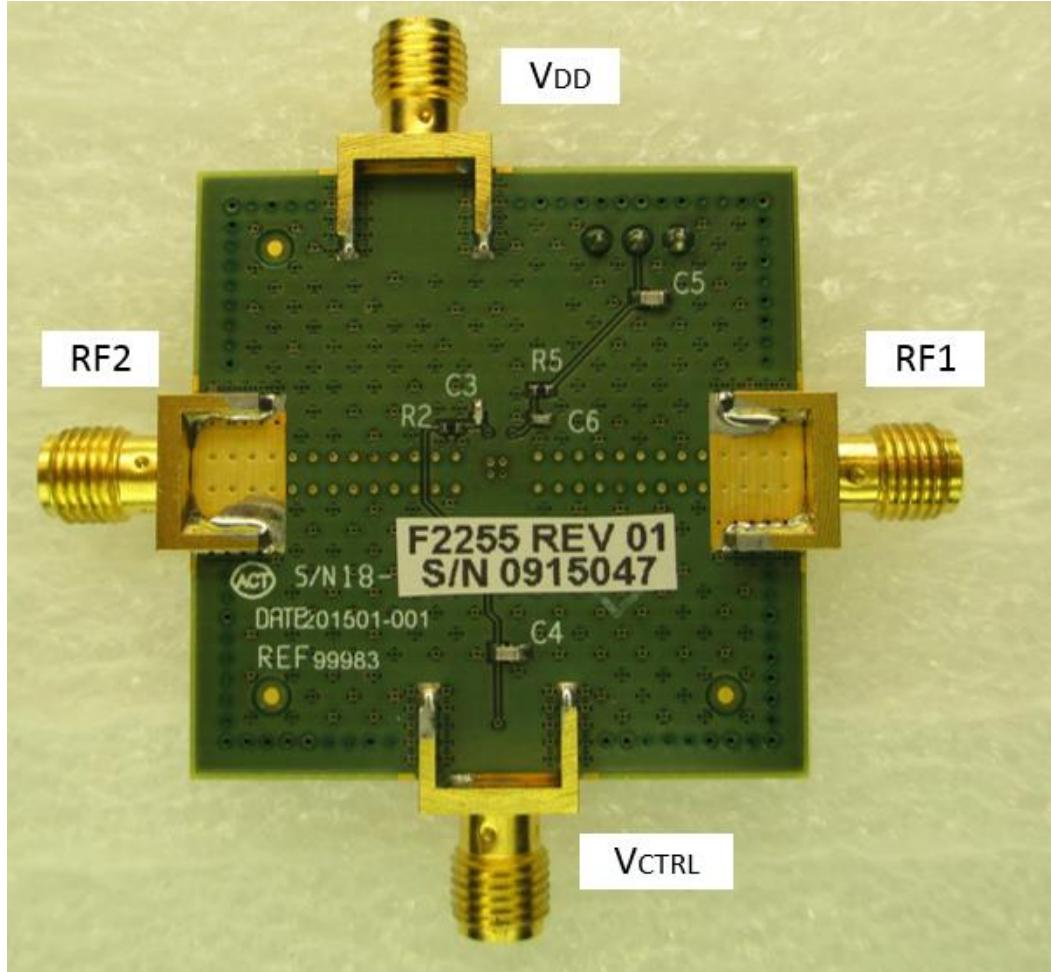
## Control Pin Interface

If control signal integrity is a concern and clean signals cannot be guaranteed due to overshoot, undershoot, ringing, etc., the following circuit at the input of control pins 14 and 16 is recommended as shown below.



**EVKIT / APPLICATIONS CIRCUIT**


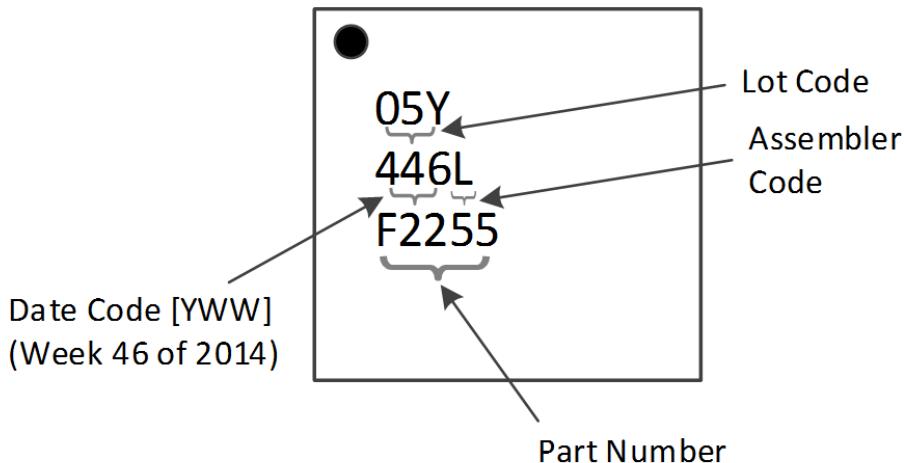
**EVKIT PICTURE / LAYOUT (TOP VIEW)**

**EVKIT PICTURE / LAYOUT (BOTTOM VIEW)**

## EVKIT BOM

Part Reference	QTY	DESCRIPTION	Mfr. Part #	Mfr.
C1, C4, C5	3	10nF ±5%, 50V, X7R Ceramic Capacitors (0603)	GRM188R71H103J	Murata
C2, C3, C6	3	1000pF ±5%, 50V, C0G Ceramic Capacitors (0402)	GRM1555C1H102J	Murata
C7, C8, C9, C10, C11	5	100nF ±10%, 16V, X7R Ceramic Capacitors (0402)	GRM155R71C104K	Murata
R1, R2, R5	3	0Ω Resistors (0402)	ERJ-2GE0R00X	Panasonic
R3, R4	2	100kΩ ±1%, 1/10W, Resistors (0402)	ERJ-2RKF1003X	Panasonic
J1, J3, J4, J5	4	Edge Launch SMA (0.375 inch pitch ground tabs)	142-0701-851	Emerson Johnson
J2	1	CONN HEADER VERT SGL 3 X 1 POS GOLD	961103-6404-AR	3M
U1	1	Voltage Variable Attenuator	F2255NLGK	IDT
	1	Printed Circuit Board	F2255 REV 1	IDT

## TOP MARKINGS



## Revision History

Revision	Revision Date	Description of Change
2	February 9, 2018	Corrected POD drawing, added revision page
1	January 30, 2017	Updated GBT limits for $I_{DD}$ , $V_{MODE}$ and $V_{CTRL}$
0	November 5, 2015	Initial Release

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