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SERIES 67B Hall Effect Joystick

FEATURES

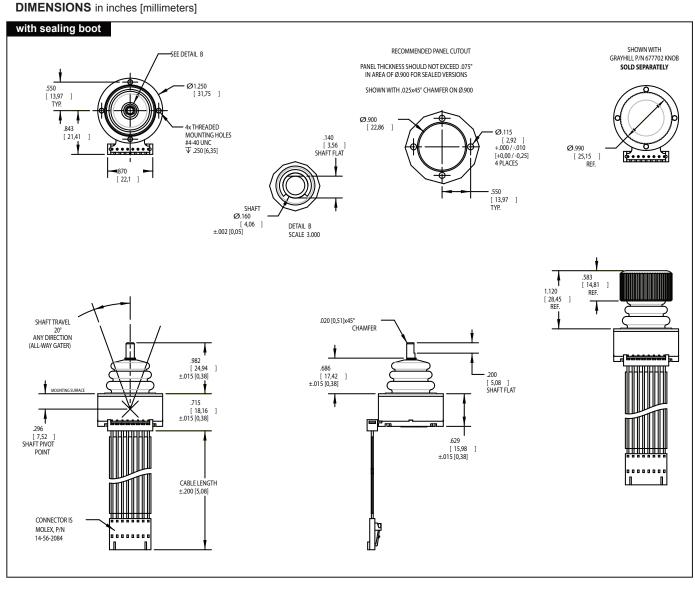
- Proportional output joystick, pushbutton, & momentary rotary select in one device
- Shaft and panel seal to IP67
- Rugged and compact: 1.25 inch diameter
- Long operational life
- RoHS compliant
- i²c output (see www.grayhill.com for User Manual)

APPLICATIONS

- Medical imaging X-ray, CT scanner, MRI patient tables
- Military vehicles display navigation
- Handheld remote control devices
- · Material handling equipment and crane operations



Actual Size

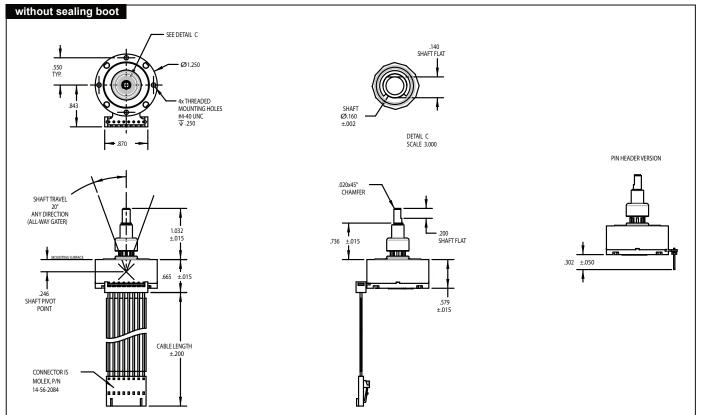


Joysticks

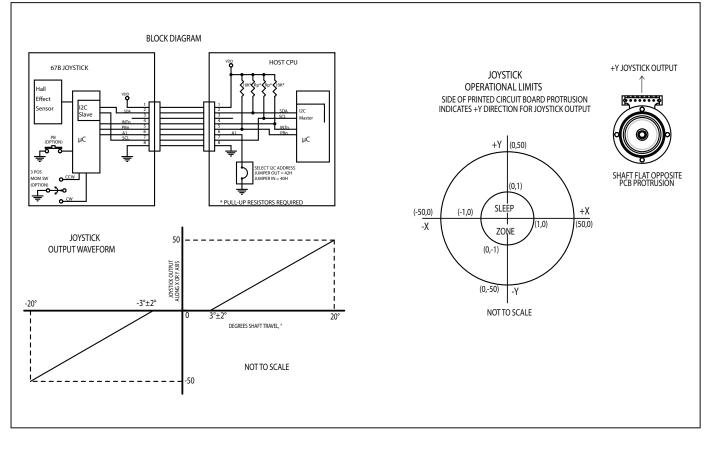


Joysticks

DIMENSIONS in inches [millimeters]



BLOCK DIAGRAM & JOYSTICK OUTPUT WAVEFORM



SPECIFICATIONS

Electrical Ratings

Supply Voltage (VVD): $3.3V \pm .0.3V$ High Level Input Voltage (VIH, Min): 0.7*VDD on SCL & SDA / 0.25*VDD+0.8 on Al Low Level Input Voltage (VIL, Max): 0.3*VDD on SCL & SDA / 0.15*VDD on Al Current Draw In Active Mode (IDDI): 3mA Maximum @ VDD = 3.3V (J & P options only) Current Draw In Sleep Mode (IDD2): 100uA Maximum @ VDD = 3.3V (J & P options only) Current Draw in Active Mode (IDD3): 4mA Maximum @ VDD = 3.3V (R option has active mode only)

Typical Operating Current: 4.0 mA at Vcc = 3.3V, T = 25°C

Maximum Operating Current: 7.0 mA over $3.0 \le Vcc \le 3.6V, -40^{\circ}C \le T \le 85^{\circ}C$ Maximum Current Sunk By Any I/O Pin: 25mA

Leakage Current: ±5 nA Typ., ±125 nA Max Low Level Output Voltage (VOL): 0.6V On INTn & SDA @ IOL = 6mA, @ VDD = 3.3V Measurement Frequency (Active Mode): 50 Samples/Sec

Response Time, Active Mode (T1): 20ms* Response Time, Sleep Mode (T2): 80ms* Output @ Maximum Joystick Deflection (XMax, YMax): 50 Units Output With Joystick Shaft Released (Center Position): (0,0) Nominal Startup Time (TP, W): 300ms

Physical & Mechanical Ratings

Vibration: Random, Meets MIL-STD-810G, Method 514.6, Procedure I Mechanical Shock: Meets per MIL-STD 202, Method 213B Test Condition A Transit Drop: Meets per MIL-ST-810G, Method 516.6, Procedure II Terminal Strength: 10 lbs. Minimum, Tested per MIL-STD-202, Method 211A Push-Out Force: 60 lbs. Minimum Pull-Out Force: 60 lbs. Minimum Shaft Impact: 0.5 lb. Weight dropped 20x from height of 1m Shaft Side-Load: 45 lbs. Minimum Mounting Torque: 3-5 in-lbs recommended, 8 in-lbs. Maximum Joystick Actuation Force: 300g Peak ± 25% Joystick Life: 1 million cycles minimum** Pushbutton Life: 1 million actuations, minimum Rotational Life: 1 million turns, minimum in each direction

Materials and Finishes

Housing: Thermoplastic Backplate: Thermoplastic Lockwashers: 304 Stainless Steel Hex Nuts: 303 Stainless Steel Shim Washers: 304 Stainless Steel Shaft: 303 Stainless Steel Cable Assembly: 26 AWG Stranded Copper Conductors Connector Body: Thermoplastic Terminals: Phosphor Bronze O-Rings: Fluorosilicone Sealing Boot: Silicone Rubber Molded over Thermoplastic Insert

Environmental Ratings

Seal: IP67, Meets IEC 60529 (sealed version only) Altitude: Tested per MIL-STD 202, Method 105C Thermal Shock: Meets MIL-STD 202, Method 107G Operating High Temperature: +85°C, Tested per IEC 68-2-14, Test Na Operating Low Temperature: -40°C, Tested per IEC 68-2-14, Test Na

Storage High Temperature: +100°C, Tested per IEC 68-2-2, Method Ba

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Storage Low Temperature: -55°C, Tested per IEC 68-2-1, Method Aa

Humidity: Meets MIL-STD 202, Method 103B Humidity, 85/85: 500 hours tested per MIL-STD 202, Method 103B

Solar Radiation: Tested per MIL-STD 810G, Method 505.5, Procedure II

Chemical Resistance: Meets ISO 16750-5 Dielectric: Meets MIL-STD 202G, Method 301 Insulation Resistance: Tested per MIL-STD 202G, Method 302

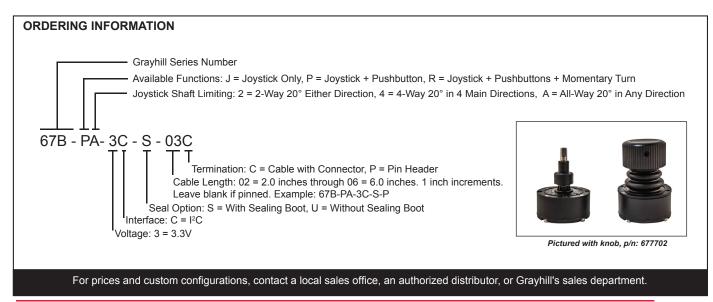
EMC Ratings

Radiated Immunity: Meets IEC 61000-4-3, 10 V/m,80 MHz-1000 MHz Conducted Immunity: Meets IEC 61000-4-6, 10 V RMS, 150 KHz to 80 MHz Radiated Emissions: Meets ANSI C63.4, er Class B Conducted Emissions: Meets EN 55022, Class B Electrostatic Discharge: Meets IEC 61000-4-2, 8 kV contact/15 kV air discharge er Power Frequency Magnetic Field: Meets IEC

Power Frequency Magnetic Field: Meets IEC 61000-4-8, 30 A/m

*Response time is the time from joystick movement to when new X,Y position data is available.

**One cycle is defined as a complete revolution of the shaft around the fixed perimeter, or one actuation in each of the 4 main directions, with return to center between each actuation.





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